

# Multi-index Sequential Monte Carlo ratio estimators for Bayesian inverse problems

**Shangda Yang**

Kody J.H. Law, Neil Walton and Ajay Jasra

ESI Workshop 1

May 5, 2022



- 1 Introduction
- 2 MLMC and MIMC
- 3 Samplers
- 4 MISMC
- 5 Numerical Results

- 1 Introduction
- 2 MLMC and MIMC
- 3 Samplers
- 4 MISMCM
- 5 Numerical Results

## Aim

We are aiming to find

$$\pi_\infty(\varphi(x)) := \mathbb{E}_{\pi_\infty}[\varphi(x)],$$

where

- $x \sim \pi_\infty$
- $\varphi(x) : \mathbb{R} \rightarrow \mathbb{R}$ .

However, we can only **approximate**  $\pi_\infty$  by  $\pi_\alpha$  with  $\alpha \in \mathbb{Z}_+^D$  being the index of refinement.

# Bayesian Inference

Under Bayesian context, the target distribution can only be evaluated up to normalising constant

$$\pi_\alpha(dx) := \pi_\alpha(dx|y) \propto L_\alpha(x)\pi_0(dx),$$

where

- $x \in \mathbb{R}^{d_x}$  is the unknown parameter
- $y \in \mathbb{R}^{d_y}$  is the observations
- $\pi_0(dx)$  is the prior distribution
- $L_\alpha(dx) \propto \pi_\alpha(y|x)$  is the approximated likelihood.

## Notations

## Exact

$$L(x) \propto \pi(y|x)$$

$$f(dx) := L(x)\pi_0(dx)$$

$$Z := \int_{\mathcal{X}} f(x)dx$$

$$\pi := \pi(dx|y) = f(dx)/Z$$

$$\pi(\varphi) := \mathbb{E}_{\pi}[\varphi(x)]$$

## Approximate

$$L_{\alpha}(x) \propto \pi_{\alpha}(y|x)$$

$$f_{\alpha}(dx) := L_{\alpha}(x)\pi_0(dx)$$

$$Z_{\alpha} := \int_{\mathcal{X}} f_{\alpha}(x)dx$$

$$\pi_{\alpha} := \pi_{\alpha}(dx|y) = f_{\alpha}(dx)/Z_{\alpha}$$

$$\pi_{\alpha}(\varphi_{\alpha}) := \mathbb{E}_{\pi_{\alpha}}[\varphi_{\alpha}(x)]$$

# Monte Carlo

Assuming can simulate samples from  $\pi_\alpha(dx|y)$ , we can construct the single level Monte Carlo estimator for  $\mathbb{E}_{\pi_\alpha}[\varphi(x)]$  as

$$N^{-1} \sum_{i=1}^N \varphi_\alpha(x^i),$$

where  $N$  is the number of samples.

**Complexity:**  $\text{MSE}^{-\xi}$  ( $\varepsilon^{-2\xi}$ ) for  $\xi > 1$  (e.g. SDE/PDE)

**Canonical:**  $\text{MSE}^{-1}$  if no discretisation bias (e.g. integral of an arbitrary function on  $[0,1]$ )

- 1 Introduction
- 2 **MLMC and MIMC**
- 3 Samplers
- 4 MISMC
- 5 Numerical Results



# Multilevel Monte Carlo (MLMC)

With **MLMC**, we apply the approximation

$$\pi(\varphi) \approx \sum_{\ell=0}^L \mathbb{E}[\varphi_{\ell}(x) - \varphi_{\ell-1}(x)], \quad (1)$$

where  $L > 0$  is the finest level of discretisation and  $\varphi_{\ell} \equiv 0$  if  $\ell < 0$ .

# Multi-index Monte Carlo (MIMC)

With **MIMC**, we apply the approximation

$$\pi(\varphi) \approx \sum_{\alpha \in \mathcal{I}} \mathbb{E}[\Delta\varphi_{\alpha}(x)], \quad (2)$$

where

- $\mathcal{I} \subset \mathbb{Z}_+^{\mathbb{D}}$
- the difference of difference operator is defined as  $\Delta\varphi_{\alpha} := \Delta_D \circ \dots \circ \Delta_1\varphi_{\alpha}$  with  $\Delta_i\varphi_{\alpha} := \varphi_{\alpha} - \varphi_{\alpha - e_i}$
- $\varphi_{\alpha} \equiv 0$  if  $\alpha_i < 0$  for any  $i$ .

E.g.  $\mathcal{D} = 2$ :

$$\Delta\varphi_{\alpha} = \varphi(u_{\alpha}(x)) - \varphi(u_{\alpha_1, \alpha_2 - 1}(x)) - \varphi(u_{\alpha_1 - 1, \alpha_2}(x)) + \varphi(u_{\alpha_1 - 1, \alpha_2 - 1}(x))$$

## MIMC

Define the vector of multi-indices:

$$\boldsymbol{\alpha}(\alpha) := (\boldsymbol{\alpha}_1(\alpha), \dots, \boldsymbol{\alpha}_{2^D}(\alpha)) \in \mathbb{Z}_+^{D \times 2^D},$$

where

- $\boldsymbol{\alpha}_1(\alpha) = \alpha$
- $\boldsymbol{\alpha}_{2^D}(\alpha) = \alpha - \sum_{i=1}^D e_i$
- $e_i$  is the  $i^{\text{th}}$  standard basis vector in  $\mathbb{R}^D$ .

Two cases:

- can sample from a coupling of  $(\pi_{\alpha_1(\alpha)}, \dots, \pi_{\alpha_{2D}(\alpha)})$  (a joint distribution with the marginal  $\pi_{\alpha_j(\alpha)}$ )  $\rightarrow$  construct a standard multi-index estimator [5]
- **cannot**  $\rightarrow$  approximate coupling and construct different estimators [7, 13]

- 1 Introduction
- 2 MLMC and MIMC
- 3 Samplers**
- 4 MISMC
- 5 Numerical Results

# Approximate Coupling

Let

- $\Pi_0(d\mathbf{x}) = \pi_0(d\mathbf{x}_1) \prod_{i=2}^{2^D} \delta_{\mathbf{x}_1}(d\mathbf{x}_i)$  ( $\delta_{\mathbf{x}_1}$  the Dirac delta function)
- $\mathbf{L}_\alpha(\mathbf{x}) = \max\{L_{\alpha_1(\alpha)}(\mathbf{x}_1), \dots, L_{\alpha_{2^D}(\alpha)}(\mathbf{x}_{2^D})\}$ .

Approximate coupling:

$$F_\alpha(d\mathbf{x}) = \mathbf{L}_\alpha(\mathbf{x})\Pi_0(d\mathbf{x}), \quad \Pi_\alpha(d\mathbf{x}) = \frac{1}{F_\alpha(1)}F_\alpha(d\mathbf{x}). \quad (3)$$

# Markov Chain Monte Carlo (MCMC)

MCMC:

- Construct an ergodic (aperiodic and positive recurrent) Markov chain such that it is  $\pi$ -invariant
- Simulate a trajectory and construct an estimator

Metropolis-Hastings method:

- Design a proposal Markov kernel  $\mathcal{M}$
- Sample  $x' \sim \mathcal{M}(x^{(i)}, \cdot)$
- Let  $x^{(i+1)} = x'$  with probability  $\min \left\{ 1, \frac{f(x')\mathcal{M}(x', x^{(i)})}{f(x^{(i)})\mathcal{M}(x^{(i)}, x')} \right\}$
- Let  $x^{(i+1)} = x^{(i)}$ , otherwise

# Sequential Monte Carlo Sampler (SMC sampler)

Sequential Monte Carlo sampler is the combination of (sequential) importance (re)sampling and Markov chain Monte Carlo.

- **Sample** from the target  $\pi$  by sampling from a simple distribution (importance sampling)
- **Mutate/Propagate** by Markov kernels to decorrelate the samples, along a sequence of distributions converging to the target (sequential importance sampling and Markov chain Monte Carlo)
- **Resample** when the effective sample size of the samples drops down to certain values (Resampling)



# Sequential Monte Carlo Sampler (SMC sampler)

Let for  $j = 1, \dots, J$

- $h_j = f_{j+1}/f_j$  where  $f_1 = \pi_0$ ,  $f_J = f$  and  $f_j$  for  $j = 2, \dots, J - 1$  are some intermediate distributions (e.g.  $f_j(x) = L(x)^{\tau_j} \pi_0(x)$ , where  $\tau_1 = 0$ ,  $\tau_j < \tau_{j+1}$ , and  $\tau_J = 1$ )
- $\pi_j(x) = \frac{1}{f_j(1)} f_j(x)$
- $\mathcal{M}_j$  be a Markov transition kernel such that  $(\pi_{\alpha,j} \mathcal{M}_j)(dx) = \pi_j(dx)$

# Sequential Monte Carlo Sampler (SMC sampler)

---

## Algorithm 1 SMC sampler

---

Let  $x_1^{(i)} \sim \pi_1$  for  $i = 1, \dots, N$ , and  $Z_1^N = 1$ . For  $j = 2, \dots, J$ , repeat the following steps:

(0) Store  $Z_j^N = Z_{j-1}^N \frac{1}{N} \sum_{k=1}^N h_{j-1}(\cdot) x_{j-1}^{(k)}$ .

For  $i = 1, \dots, N$ :

- (i) Define  $w_j^i = h_{j-1}(\cdot) x_{j-1}^{(i)} / \sum_{k=1}^N h_{j-1}(\cdot) x_{j-1}^{(k)}$ .
  - (ii) Resample. Select  $l_j^i \sim \{w_j^1, \dots, w_j^N\}$ , and let  $\hat{x}_j^{(i)} = x_{j-1}^{(l_j^i)}$ .
  - (iii) Mutate. Draw  $x_j^{(i)} \sim \mathcal{M}_j(\hat{x}_j^{(i)}, \cdot)$ .
-

- 1 Introduction
- 2 MLMC and MIMC
- 3 Samplers
- 4 MISMIC**
- 5 Numerical Results

## Multi-index sequential Monte Carlo (MIMC):

MIMC + SMC sampler + Estimators

Estimators { self-normalised (SN) increments estimator  
ratio estimator

## Self-normalised increments estimator

Self-normalised increments estimator (**lack of rigorous convergence results for realistic assumptions**):

$$\pi(\varphi) \approx \sum_{\alpha \in \mathcal{I}} \Delta(\pi_{\alpha}(\varphi_{\alpha})) = \sum_{\alpha \in \mathcal{I}} \Delta \left( \frac{1}{Z_{\alpha}} f_{\alpha}(\varphi_{\alpha}) \right) \quad (4)$$

- Sample from the approximate coupling (3) using SMC sampler
- Construct the self-normalized importance sampling estimators

$$\Delta \left( \frac{\sum_{i=1}^N \varphi_{\alpha}(x^{(i)}) \frac{\pi_{\alpha}(x^{(i)})}{\Pi_{\alpha}(x^{(i)})}}{\sum_{i=1}^N \frac{\pi_{\alpha}(x^{(i)})}{\Pi_{\alpha}(x^{(i)})}} \right), \quad x^{(i)} \sim \Pi_{\alpha}$$

for each individual summands of (4)

# Self-normalised increments estimator assumption

(A2) For every  $n \geq 0$ ,  $\varphi : \mathbb{N}_0^d \times \mathcal{X}^{n+1} \times \Theta \rightarrow \mathbb{R}$  bounded, every  $\alpha \in \mathcal{I}$ , there exist a  $C(\alpha(1 : k_\alpha))$ , with  $\lim_{\min_1 \leq i \leq d} \alpha_i \rightarrow +\infty} C(\alpha(1 : k_\alpha)) = 0$ , such that for any collection of scalar, bounded random variables  $\beta(\alpha(1 : k_\alpha), 2i, 2i - 1)$ ,  $i \in \{1, \dots, k'_\alpha\}$  we have almost surely

$$\sup_{(x_{0:n}(1:k_\alpha), \theta) \in (\otimes_{i=1}^{k_\alpha} \mathcal{X}_{\alpha(i)}^{n+1}) \times \Theta} \left| \left\{ \sum_{i=1}^{k'_\alpha} \tau_{i,\alpha} \beta(\alpha(1 : k_\alpha), 2i, 2i - 1) \left[ \varphi_{\alpha(2i)}(x_{0:n}(1 : k_\alpha), \theta) - \varphi_{\alpha(2i-1)}(x_{0:n}(1 : k_\alpha), \theta) \right] \right\} \right| \leq C(\alpha(1 : k_\alpha)) \sum_{i=1}^{k'_\alpha} |\beta(\alpha(1 : k_\alpha), 2i, 2i - 1)|^2.$$

# Ratio estimator

Ratio estimator (by ratio decomposition)

$$\pi(\varphi) = \frac{f(\varphi)}{f(1)} \approx \frac{\sum_{\alpha \in \mathcal{I}} \Delta(f_{\alpha}(\varphi))}{\sum_{\alpha \in \mathcal{I}} \Delta(f_{\alpha}(1))} \quad (5)$$

- Sample from the approximate coupling (3) using SMC sampler
- Construct estimators for the unnormalised increments  $\Delta(f_{\alpha}(\zeta_{\alpha}))$  for  $\zeta_{\alpha} = \varphi_{\alpha}$  and  $\zeta_{\alpha} = 1$

# Estimators for the unnormalised increments of increments

Define for  $j = 1, \dots, J$ , and for random variables  $\mathbf{x}_j^{(i)}$ ,  $i = 1, \dots, N$

- $\Pi_{\alpha,j}^N(d\mathbf{x}) := \frac{1}{N} \sum_{i=1}^N \delta_{\mathbf{x}_j^{(i)}}(d\mathbf{x})$
- $H_{\alpha,j} = F_{\alpha,j+1}/F_{\alpha,j}$
- $Z_\alpha^N := \prod_{j=1}^{J-1} \Pi_{\alpha,j}^N(H_{\alpha,j})$
- $F_\alpha^N(d\mathbf{x}) := Z_\alpha^N \Pi_{\alpha,J}^N(d\mathbf{x})$
- $\psi_{\zeta_\alpha}(\mathbf{x}) := \sum_{k=1}^{2^D} \iota_k \omega_k(\mathbf{x}) \zeta_{\alpha_k(\alpha)}(\mathbf{x}_k)$ ,  $\omega_k(\mathbf{x}) := \frac{L_{k(\alpha)}(\mathbf{x}_k)}{\mathbf{L}_\alpha(\mathbf{x})}$ ,  
where  $\iota_k \in \{-1, 1\}$  is the sign of the  $k^{\text{th}}$  term in  $\Delta f_\alpha$ .



# Ratio Estimator

The ratio estimator is

$$\widehat{\varphi}_{\mathcal{I}}^{\text{MI}} = \frac{\sum_{\alpha \in \mathcal{I}} F_{\alpha}^{N_{\alpha}}(\psi_{\varphi_{\alpha}})}{\max\{\sum_{\alpha \in \mathcal{I}} F_{\alpha}^{N_{\alpha}}(\psi_1), Z_{\min}\}},$$

where

- $\mathcal{I} \subseteq \mathbb{Z}_+^D$  is the index set
- $\{N_{\alpha}\}_{\alpha \in \mathcal{I}}$  are the number of samples
- $\varphi : X \rightarrow \mathbb{R}$  is the quantity of interest
- $Z_{\min}$  is a lower bound on  $Z$ .

# Estimators for the unnormalised increments of increments

Note:

The estimator  $F_\alpha^N(\psi_{\zeta_\alpha})$  is **unbiased**

$$\mathbb{E}[F_\alpha^N(\psi_{\zeta_\alpha})] = F_\alpha(\psi_{\zeta_\alpha}) = \Delta f_\alpha(\zeta_\alpha)$$

# Estimators for the unnormalised increments of increments

## Assumption 4.1

Let  $J \in \mathbb{N}$  be given. For each  $j \in \{1, \dots, J\}$  there exists some  $C > 0$  such that for all  $(\alpha, x) \in \mathbb{Z}_+^D \times X$

$$C^{-1} < Z, H_{\alpha,j}(x) \leq C.$$

## Assumption 4.2

For any  $\zeta : \rightarrow$  bounded and Lipschitz, there exist  $C, \beta_i, s_i, \gamma_i > 0$  for  $i = 1, \dots, D$  such that for resolution vector  $(2^{-\alpha_1}, \dots, 2^{-\alpha_D})$ , i.e. resolution  $2^{-\alpha_i}$  in the  $i^{\text{th}}$  direction, the following holds

(B)  $|f_\alpha(\zeta) - f(\zeta)| =: B_\alpha \leq C 2^{-\langle \alpha, s \rangle};$

(V)  $\int_X (\Delta(L_\alpha(x)\zeta_\alpha(x)))^2 \pi_0(dx) =: V_\alpha \leq C 2^{-\langle \alpha, \beta \rangle};$

(C)  $\text{COST}(F_\alpha(\psi_\varphi)) =: C_\alpha \propto 2^{\langle \alpha, \gamma \rangle}.$



## Multi-index sequential Monte Carlo ratio estimator

## Theorem 1

Assume 4.1. Then for any  $J \in \mathbb{N}$  there exists a  $C > 0$  such that for any  $N \in \mathbb{N}$ ,  $\psi : X^{2^D} \rightarrow \mathbb{R}$  bounded and measurable and  $\alpha \in \mathbb{Z}_+^D$

$$\mathbb{E} \left[ |F_\alpha^N(\psi) - F_\alpha(\psi)|^2 \right] \leq \frac{C}{N} F_\alpha(\psi^2).$$

## Lemma 4.1

Assume 4.1. Then there exist a  $C > 0$  such that for any  $\alpha \in \mathbb{Z}_+^D$

$$F_\alpha(\psi_{\zeta_\alpha}^2) \leq C \int_X (\Delta(L_\alpha(x)\zeta_\alpha(x)))^2 \pi_0(dx).$$

## MISMICRE with the tensor product index set

## Theorem 2

Assume 4.1 and 4.2, with  $\sum_{j=1}^D \frac{\gamma_j}{s_j} \leq 2$  and  $\beta_i > \gamma_i$  for  $i = 1, \dots, D$ . Then for any  $\varepsilon > 0$  and suitable  $\varphi : X \rightarrow \mathbb{R}$ , it is possible to choose a tensor product (TP) index set  $\mathcal{I}_{L_1:L_D} := \{\alpha \in \mathbb{N}^D : \alpha_1 \in \{0, \dots, L_1\}, \dots, \alpha_D \in \{0, \dots, L_D\}\}$  and  $\{N_\alpha\}_{\alpha \in \mathcal{I}_{L_1:L_D}}$ , such that for some  $C > 0$

$$\mathbb{E}[(\hat{\varphi}_{\mathcal{I}}^{\text{MI}} - \pi(\varphi))^2] \leq C\varepsilon^2,$$

and  $\text{COST}(\hat{\varphi}_{\mathcal{I}}^{\text{MI}}) \leq C\varepsilon^{-2}$ , the *canonical* rate.

## MISMCRE with the total degree index set

## Theorem 3

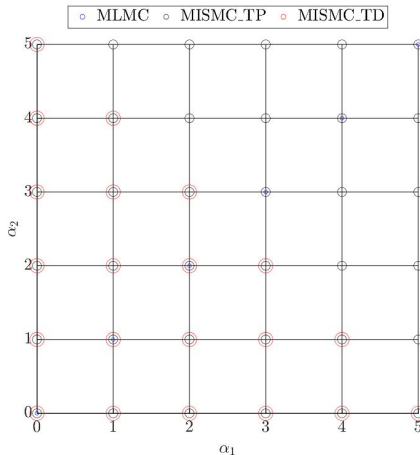
Assume 4.1 and 4.2, with  $\beta_i > \gamma_i$  for  $i = 1, \dots, D$ . Then for any  $\varepsilon > 0$  and suitable  $\varphi : X \rightarrow \mathbb{R}$ , it is possible to choose a total degree (TD) index set

$\mathcal{I}_L := \{\alpha \in \mathbb{N}^D : \sum_{i=1}^D \delta_i \alpha_i \leq L, \sum_{i=1}^D \delta_i = 1\}$ ,  $\delta_i \in (0, 1]$  and  $\{N_\alpha\}_{\alpha \in \mathcal{I}_L}$ , such that for some  $C > 0$

$$\mathbb{E}[(\hat{\varphi}_{\mathcal{I}}^{\text{MI}} - \pi(\varphi))^2] \leq C\varepsilon^2,$$

and  $\text{COST}(\hat{\varphi}_{\mathcal{I}}^{\text{MI}}) \leq C\varepsilon^{-2}$ , the *canonical* rate.

# Index sets



# Crucial point for theoretical results

## Lemma 4.2

For the estimator  $\widehat{\varphi}_{\mathcal{I}}^{\text{MI}} = \frac{\sum_{\alpha \in \mathcal{I}} F_{\alpha}^{N_{\alpha}}(\psi_{\varphi_{\alpha}})}{\max\{\sum_{\alpha \in \mathcal{I}} F_{\alpha}^{N_{\alpha}}(\psi_1), Z_{\min}\}}$ , the following inequality holds

$$\mathbb{E}[(\widehat{\varphi}_{\mathcal{I}}^{\text{MI}} - \pi(\varphi))^2] \leq C \max_{\zeta \in \{\varphi, 1\}} \left( \sum_{\alpha \in \mathcal{I}} \mathbb{E} \left[ \left( F_{\alpha}^{N_{\alpha}}(\psi_{\zeta_{\alpha}}) - F_{\alpha}(\psi_{\zeta_{\alpha}}) \right)^2 \right] + \left( \sum_{\alpha \notin \mathcal{I}} F_{\alpha}(\psi_{\zeta_{\alpha}}) \right)^2 \right),$$

for some  $C > 0$ .



# Sub-canonical and Canonical

MISMCM with TP index set:

- relies on the assumption that  $\sum_{j=1}^D \frac{\gamma_j}{s_j} \leq 2$  (the samples at the finest index do not dominate the cost)
- if assumption is violated, only **sub-canonical** complexity
- sub-canonical rate may often be D-dependent (curse-of-dimensionality)

MISMCM with TD index set:

- releases this constraint
- improves the computational complexity for many problems from sub-canonical to **canonical**

- 1 Introduction
- 2 MLMC and MIMC
- 3 Samplers
- 4 MISMC
- 5 Numerical Results**

## Elliptic PDEs

We consider the following elliptic PDE,

$$-\nabla \cdot (a(x)\nabla u(x)) = f, \quad \text{on } \Omega, \quad (6)$$

$$u(x) = 0, \quad \text{on } \partial\Omega, \quad (7)$$

where

- $\Omega \subset \mathbb{R}^D$  is a convex domain
- $\partial\Omega \in C^0$  is the boundary
- $f : \Omega \rightarrow \mathbb{R}$
- $a(x) : \Omega \rightarrow \mathbb{R}_+$ , parameterised by a random variable  $x \in X$ .

We solve the PDE by the **finite element method**.

## Bayesian settings

- Define

$$\mathcal{G}(u(x)) = [v_1(u(x)), \dots, v_m(u(x))]^\top,$$

where  $v_i \in L^2$  and  $v_i(u(x)) = \int v_i(z)u(x)(z)dz$  for  $i = 1, \dots, m$ , for some  $m \geq 1$ .

- Assume the observations take the form

$$y = \mathcal{G}(u(x)) + \nu,$$

where  $\nu \sim N(0, \Xi)$ , and  $x$  and  $\nu$  are independent.

- Define

$$L(x) := \exp\left(-\frac{1}{2}|y - \mathcal{G}(u(x))|_{\Xi}^2\right) \propto \pi(y|x),$$

where  $|w|_{\Xi} := (w^\top \Xi^{-1} w)^{1/2}$

# Bayesian Settings

Denote the weak approximation of (6)-(7) at resolution multi-index  $\alpha$  by  $u_\alpha(x)$ , the approximated likelihood is given by

$$L_\alpha(x) := \exp\left(-\frac{1}{2}|y - \mathcal{G}(u_\alpha(x))|_{\underline{\Xi}}^2\right),$$

and the associated target is

$$\pi_\alpha(dx) \propto L_\alpha(x)\pi_0(dx). \quad (8)$$

# 1D Toy Example

PDE:

- $\Omega = [0, 1]$
- $a(x) = 1$
- $f = x$ , where  $x$  is a random input with a uniform prior such that  $x \sim U[-1, 1]$
- analytical solution  $u(x) = -0.5x(z^2 - z)$

Observations:

- ten observations in the interval  $(0, 1)$  with a step size  $1/10$
- generated by  $y = -0.5x^*(z^2 - z) + \nu$ , where  $y = [y_1, \dots, y_{10}]$ ,  $z = [z_1, \dots, z_{10}]$ ,  $x^* = 0.2581$  drawn from  $U[-1, 1]$  and  $\nu \sim N(0, 0.2^2)$ .

# 1D Toy Example

Regularity:

- $s = 2, \beta = 4, \gamma = 1$

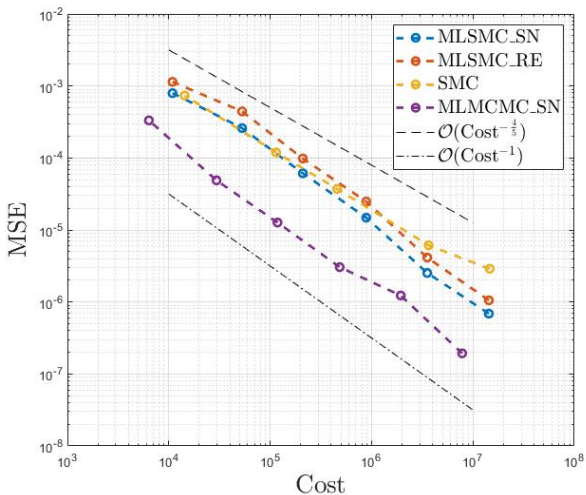
Quantity of interest:

- $\varphi(x) = x^2$

Complexity:

- Multilevel methods:  $\text{MSE}^{-1}$
- Single level method:  $\text{MSE}^{-4/5}$

# 1D Toy Example





## 2D Elliptic PDE with random diffusion coefficient

PDE:

- $\Omega = [0, 1]^2$
- $a(x) = 3 + x_1 \cos(3z_1) \sin(3z_2) + x_2 \cos(z_1) \sin(z_2)$ , where  $x$  is a random input with a uniform prior such that  $x \sim U[-1, 1]^2$
- $f = 100$

Observations:

- four observations  $\{(0.25, 0.25), (0.25, 0.75), (0.75, 0.25), (0.75, 0.75)\}$
- generated by  $y = u_\alpha(x^*) + \nu$ , where  $u_\alpha(x^*)$  is the approximate solution of the PDE at  $\alpha = [10, 10]$  with  $x^* = [-0.4836, -0.5806]$  drawn from  $U[-1, 1]^2$ , and  $\nu \sim N(0, 0.5^2)$ .

## 2D Elliptic PDE with random diffusion coefficient

Regularity:

- $s_1 = s_2 = 2, \beta_1 = \beta_2 = 4, \gamma_1 = \gamma_2 = 1$

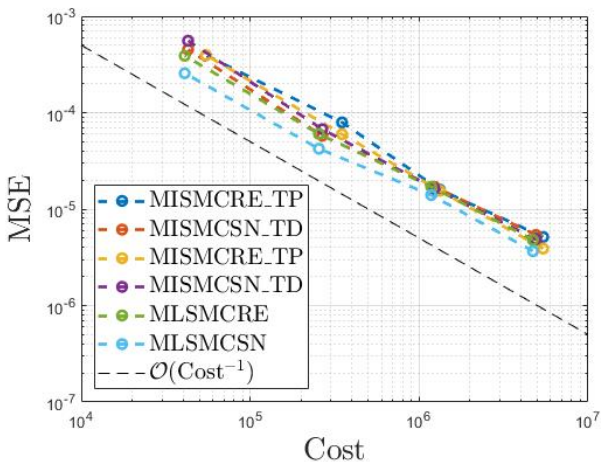
Quantity of interest:

- $\varphi(x) = x_1^2 + x_2^2$

Complexity:

- Multilevel and multi-index methods:  $\text{MSE}^{-1}$
- Single level method:  $\text{MSE}^{-2/3}$

# 2D Elliptic PDE with random diffusion coefficient



# Log Gaussian (Cox) Process models [6, 10][12]

Observations: the location of  $n = 126$  Scots pine saplings in a natural forest in Finland, denoted  $z_1, \dots, z_n \in [0, 1]^2$ .

Process applied:  $\Lambda = \exp(x)$  where  $x$  is a Gaussian process (a priori), for  $z \in [0, 2]^2$ ,

$$x(z) = \theta_1 + \sum_{k \in \mathbb{Z} \times \mathbb{Z}_+ \cup \mathbb{Z}_+ \times 0} \zeta_k(\theta) (\xi_k \phi_k(z) + \xi_k^* \phi_{-k}(z)),$$

where

- $\xi_k \sim \mathcal{CN}(0, 1)$  i.i.d. and  $\xi_k^*$  is the complex conjugate of  $\xi_k$
- $\mathcal{CN}(0, 1)$  denotes a standard complex Normal distribution
- $\phi_k(z) \propto \exp[\pi i z \cdot k]$  are Fourier series basis functions
- $\zeta_k^2(\theta) = \theta_2 / ((\theta_3 + k_1^2)(\theta_3 + k_2^2))^{\frac{\beta+1}{2}}$ .

## Likelihoods

$$(LGC) \quad \frac{d\pi}{d\pi_0}(x) \propto \exp \left[ \sum_{j=1}^n x(z_j) - \int_{[0,1]^2} \exp(x(z)) dz \right],$$

$$(LGP) \quad \frac{d\pi}{d\pi_0}(x) \propto \exp \left[ \sum_{j=1}^n x(z_j) - n \log \int_{[0,1]^2} \exp(x(z)) dz \right].$$

# Finite Approximation

Finite approximation of  $x(z)$ :

$$x_\alpha(z) = \theta_1 + \sum_{k \in \mathcal{A}_\alpha} \zeta_k(\theta) (\xi_k \phi_k(z) + \xi_k^* \phi_{-k}(z)), \quad \xi_k \sim \mathcal{CN}(0, 1) \text{ i.i.d.},$$

where

$$\mathcal{A}_\alpha := \{-2^{\alpha_1/2}, \dots, 2^{\alpha_1/2}\} \times \{1, \dots, 2^{\alpha_2/2}\} \cup \{1, \dots, 2^{\alpha_2/2}\} \times 0$$

and can be approximated on a grid

$\{0, 2^{-\alpha_1}, \dots, 1 - 2^{-\alpha_1}\} \times \{0, 2^{-\alpha_2}, \dots, 1 - 2^{-\alpha_2}\}$  using the FFT  
with a cost  $\mathcal{O}((\alpha_1 + \alpha_2)2^{\alpha_1 + \alpha_2})$ .

# Finite Approximation

Finite approximation of the likelihood:

$$(LGC) \quad \frac{d\pi_\alpha}{d\pi_{0,\alpha}}(x_\alpha) \propto \exp \left[ \sum_{j=1}^n \hat{x}_\alpha(z_j) - Q(\exp(x_\alpha)) \right],$$

$$(LGP) \quad \frac{d\pi_\alpha}{d\pi_{0,\alpha}}(x_\alpha) \propto \exp \left[ \sum_{j=1}^n \hat{x}_\alpha(z_j) - n \log Q(\exp(x_\alpha)) \right],$$

where  $\hat{x}_\alpha(z)$  is defined as an interpolant over the grid output from FFT and  $Q$  denotes a quadrature rule.

# Log Gaussian (Cox) Process Models

Parameters for LGC:

- $\beta = 1.6$ ,  $\theta = (\theta_1, \theta_2, \theta_3) = (0, 1, 110.339)$

Parameters for LGP:

- $\beta = 1.6$ ,  $\theta = (\theta_1, \theta_2, \theta_3) = (0, 1, 27.585)$

Regularity:

- $s_1 = s_2 = 0.8$ ,  $\beta_1 = \beta_2 = 1.6$ ,  $\gamma_1 = \gamma_2 = 1 + \omega$  for  $\omega > 0$

Quantity of interest:

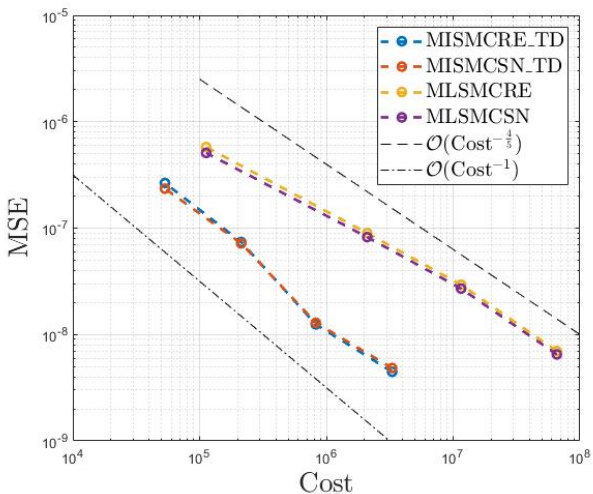
- $\varphi(x) = \int_{[0,1]^2} \exp(x(z)) dz$

Complexity:

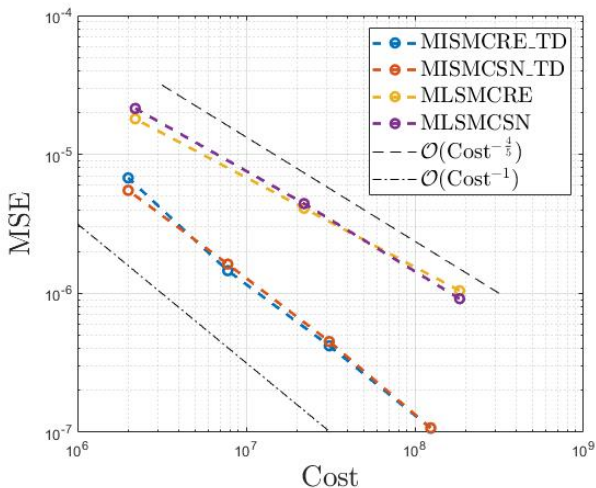
- Grid-based approach: approximately  $\text{MSE}^{-19/4}$
- Single level method with circulant embedding: approximately  $\text{MSE}^{-9/4}$
- MLSMC or MISMC with TP set:  $\text{MSE}^{-5/4-\omega}$
- MISMC with TD set:  **$\text{MSE}^{-1}$**



# Log Gaussian Cox Process Model



# Log Gaussian Process Model



# Summary

- MISMCRE has rigorous **theoretical results under realistic assumptions** due to the unbiased estimation of the unnormalised increments of increments.
- MISMCRE with TD set can improve the complexity of MLSMCRE and MISMCRE with TP set from subcanonical to **canonical** for some problems.

## References I

- [1] Alexandros Beskos, Ajay Jasra, Kody J. H. Law, Raul Tempone, and Yan Zhou. “Multilevel sequential Monte Carlo samplers”. In: *Stochastic Processes and their Applications* 127.5 (2017), pp. 1417–1440.
- [2] T. Cui, Ajay Jasra, and Kody J. H. Law. “Multi-Index Sequential Monte Carlo methods”. In: *Preprint* (2018).
- [3] Pierre Del Moral, Arnaud Doucet, and Ajay Jasra. “Sequential Monte Carlo samplers”. In: *Journal of the Royal Statistical Society: Series B (Statistical Methodology)* 68.3 (2006), pp. 411–436.
- [4] Michael B Giles. “Multilevel Monte Carlo methods”. In: *Acta Numerica* 24 (2015), p. 259.
- [5] Abdul-Lateef Haji-Ali, Fabio Nobile, and Raúl Tempone. “Multi-index Monte Carlo: when sparsity meets sampling”. In: *Numerische Mathematik* 132.4 (2016), pp. 767–806.

## References II

- [6] Jeremy Heng, Adrian N Bishop, George Deligiannidis, and Arnaud Doucet. “Controlled sequential monte carlo”. In: *The Annals of Statistics* 48.5 (2020), pp. 2904–2929.
- [7] Ajay Jasra, Kengo Kamatani, Kody J. H. Law, and Yan Zhou. “A multi-index Markov chain Monte Carlo method”. In: *International Journal for Uncertainty Quantification* 8.1 (2018).
- [8] Ajay Jasra, Kengo Kamatani, Kody J. H. Law, and Yan Zhou. “Bayesian static parameter estimation for partially observed diffusions via multilevel Monte Carlo”. In: *SIAM Journal on Scientific Computing* 40.2 (2018), A887–A902.
- [9] Ajay Jasra, Kengo Kamatani, Kody JH Law, and Yan Zhou. “Multilevel particle filters”. In: *SIAM Journal on Numerical Analysis* 55.6 (2017), pp. 3068–3096.

## References III

- [10] Jesper Møller, Anne Randi Syversveen, and Rasmus Plenge Waagepetersen. “Log gaussian cox processes”. In: *Scandinavian journal of statistics* 25.3 (1998), pp. 451–482.
- [11] Andrew M Stuart. “Inverse problems: a Bayesian perspective”. In: *Acta numerica* 19 (2010), pp. 451–559.
- [12] Surya T Tokdar and Jayanta K Ghosh. “Posterior consistency of logistic Gaussian process priors in density estimation”. In: *Journal of statistical planning and inference* 137.1 (2007), pp. 34–42.
- [13] Yaxian Xu, Ajay Jasra, and Kody JH Law. “Multi-Index Sequential Monte Carlo Methods for partially observed Stochastic Partial Differential Equations”. In: *arXiv preprint arXiv:1805.00415* (2018).

# Thank You!

Paper: <https://arxiv.org/abs/2203.05351>

Codes: <https://github.com/Shangda-Yang/MISMICRE.git>