

Singular kinetic equations

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1 Background and Motivations

2 Linear equation

3 Nonlinear equation

4 Singular DDSDE

Motivation-(Mean field limit/DDSDE)

- Consider the following **second order** interacting particle systems:

$$\begin{cases} dX_t^i = V_t^i dt, \\ dV_t^i = b(Z_t^i) dt + \frac{1}{N} \sum_{j \neq i} K(X_t^i - X_t^j) dt + \sqrt{2} dB_t^i, \end{cases}$$

where $i = 1, 2, \dots, N$,

$Z^i = (X^i, V^i) \in \mathbb{R}^{2d}$: position and velocity of particle number i

B_t^i : independent Brownian motions

b : the random environment depending on Z^i .

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- Letting $N \rightarrow \infty$, we obtain the following Distribution Dependent SDE(DDSDE, also called McKean-Vlasov equation):

$$\begin{cases} dX_t = V_t dt \\ dV_t = b(Z_t) dt + \int_{\mathbb{R}^d} K(X_t - y) \mu_t(dy) dt + \sqrt{2} dB_t \\ Z_0 \sim u_0 dx dv, \end{cases} \quad (1)$$

where $Z_t = (X_t, V_t)$, μ_t is the distribution of X_t and B_t is a standard BM.

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- When b, K are smooth, well-posedness of solutions and propagation of chaos hold

Problem

- Formally, by Itô's formula, the law of solution to DDSDE = the limit u of the empirical measure $u_N := \frac{1}{N} \sum_{i=1}^N \delta_{(X_t^i, V_t^i)}$ solves the following **kinetic** equation

$$\partial_t u = \Delta_v u - v \cdot \nabla_x u - \operatorname{div}_v((b + K * \langle u \rangle)u), \quad u(0) = u_0, \quad (2)$$

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Global well-posedness of DDSDE (1)? Nonlinear martingale problem.

Kinetic equation

- Consider the following linear kinetic equation:

$$\mathcal{L}u := (\partial_t \pm v \cdot \nabla_x - \Delta_v)u = f \quad \text{on} \quad \mathbb{R}^+ \times \mathbb{R}^{2d}.$$

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- Scaling transform:** for $\lambda > 0$ and $a, b, c > 0$, let

$$u_\lambda(t, x, v) := \lambda^a u(\lambda^b t, \lambda^c x, \lambda v), \quad f_\lambda(t, x, v) := f(\lambda^b t, \lambda^c x, \lambda v).$$

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$$\|f\|_{\mathbf{C}_a^\alpha} := \|f\|_{L^\infty} + \sup_{z \neq 0} \frac{\|f(\cdot + z) - f\|_{L^\infty}}{|z|_a^\alpha}, \quad 0 < \alpha < 1$$

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- Kinetic semigroup

$$P_t f(z) := \Gamma_t p_t * \Gamma_t f(z) = \Gamma_t (p_t * f)(z) \quad \text{and} \quad \mathcal{I}f := \int_0^t P_{t-s} f ds$$

is a solution to the above equation, where $\Gamma_t f(z) := f(\Gamma_t z)$, $\Gamma_t z := (x + tv, v)$, p_t the density of $(\sqrt{2} \int_0^t W_s ds, \sqrt{2} W_t)$.

Difficulty

- Consider the following nonlinear kinetic equation

$$\partial_t u = \Delta_v u + v \cdot \nabla_x u + b \cdot \nabla_v u + K * \langle u \rangle \cdot \nabla_v u + f, \quad u(0) = u_0, \quad (4)$$

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$$b \in L_T^\infty \mathbf{C}_a^{-\alpha}(\rho_\kappa), \quad f \in L_T^\infty \mathbf{C}_a^{-\alpha}(\rho_\kappa),$$

where $\rho_\kappa(x, v) := ((1 + |x|^2)^{1/3} + (1 + |v|^2)^{-\kappa/2})$, $\mathbf{C}_a^{-\alpha}(\rho_\kappa) = \{f : f\rho_\kappa \in \mathbf{C}_a^{-\alpha}\}$.

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- Difficulty:** the best regularity of the solution is in $L_T^\infty \mathbf{C}_a^{2-\alpha}$.
(Ill-defined problem) $b \cdot \nabla_v u$ does not make sense since

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- Aim:** develop paracontrolled calculus to get global well-posedness of (4)

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- Consider the following linear kinetic PDE:

$$\mathcal{L}u := (\partial_t - \Delta_v - v \cdot \nabla_x)u = b \cdot \nabla_v u + f, \quad u(0) = u_0. \quad (5)$$

- Suppose that for some $\alpha \in (\frac{1}{2}, \frac{2}{3})$ and $\rho_\kappa, (b, f) \in L_T^\infty \mathbf{C}_a^{-\alpha}(\rho_\kappa)$.
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- Kinetic Hölder space: $\alpha \in (0, 2), T > 0$.

$$\mathbb{S}_{T,a}^\alpha(\rho) := \left\{ f : \|f\|_{\mathbb{S}_{T,a}^\alpha(\rho)} := \|f\|_{L_T^\infty \mathbf{C}_a^\alpha(\rho)} + \|f\|_{\mathbf{C}_{T,\Gamma}^{\alpha/2} L^\infty(\rho)} < \infty \right\},$$

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- Recall $P_t f = \Gamma_t(\rho_t * f), P_t f - \Gamma_t f = \Gamma_t(\rho_t * f - f)$
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 - $\Gamma_t f - f = f(x + tv, v) - f(x, v)$
- Schauder estimates: $\|\mathcal{I}f\|_{\mathbb{S}_{T,a}^{2-\beta}(\rho)} \lesssim \|f\|_{L_T^\infty \mathbf{C}_a^{-\beta}(\rho)},$ for $\mathcal{I} = (\mathcal{L})^{-1}, \beta \in (0, 2)$.

Paracontrolled solution to linear PDE

- Paraproducts: if $f \in C_a^\alpha, g \in C_a^\beta$ for $\alpha > 0, \beta < 0$

$$fg = \underbrace{f \prec g}_{\text{bad term}} + \underbrace{f \circ g}_{\text{well defined only if } \alpha + \beta > 0} + f \succ g,$$

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- Paracontrolled solution: $\mathcal{I} = (\mathcal{L})^{-1}$

$$u = \nabla_v u \prec \mathcal{I}b + \underbrace{u^\sharp}_{\text{regular term}} + \mathcal{I}f, \quad \text{paracontrolled ansatz}$$

$$u^\sharp = \mathcal{I}(\nabla_v u \succ b + b \circ \nabla_v u) - [\mathcal{I}, \nabla_v u \prec]b.$$

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- Aim:** Commutator estimate for $[\mathcal{I}, \nabla_v u \prec]b$

Commutator estimate for kinetic operator

Recall $P_t = \Gamma_t p_t * \Gamma_t$ be the kinetic semigroup.

Lemma 2.1

For any $\alpha \in (0, 1)$, $\beta \in \mathbb{R}$, $t \in (0, T]$, $\delta \geq 0$, $j \geq -1$,

$$\|\Delta_j [P_t(f \prec g) - (\Gamma_t f \prec P_t g)]\|_{L^\infty(\rho_1 \rho_2)} \lesssim t^{-\frac{\delta}{2}} 2^{-(\alpha + \beta + \delta)j} \|f\|_{\mathbf{C}_a^\alpha(\rho_1)} \|g\|_{\mathbf{C}_a^\beta(\rho_2)}.$$

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\Rightarrow

Lemma 2.2

Commutator estimate

$$\|[\mathcal{I}_\lambda, f \prec]g\|_{L_T^\infty \mathbf{C}_a^{\alpha+\beta+2}(\rho_1 \rho_2)} \lesssim \|f\|_{\mathbb{S}_{T,a}^\alpha(\rho_1)} \|g\|_{L_T^\infty \mathbf{C}_a^\beta(\rho_2)}. \quad (6)$$

$$\Rightarrow u \in C_T \mathbf{C}_a^{2-\alpha}(\rho_\delta), u^\sharp \in C_T \mathbf{C}_a^{3-2\alpha}(\rho_\delta)$$

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- If $b \circ \nabla_v \mathcal{I} b, b \circ \nabla_v \mathcal{I} f \in L_T^\infty \mathbf{C}_a^{1-2\alpha}(\rho_\kappa)$

Renormalization

- If $b \circ \nabla_v \mathcal{I} b, b \circ \nabla_v \mathcal{I} f \in L_T^\infty \mathbf{C}_a^{1-2\alpha}(\rho_\kappa) \Rightarrow b \circ \nabla u \in L_T^\infty \mathbf{C}_a^{1-2\alpha}(\rho_\kappa)$ by **commutator estimate** and paracontrolled ansatz

Renormalization

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- **Interesting point:** 0th Wiener chaos is not constant but converges after minus a formally diverging term, which is zero by symmetry \Rightarrow **No renormalization**

Well-posedness of linear PDE

$$(\partial_t - \Delta_v - v \cdot \nabla_x)u = b \cdot \nabla_v u + f, \quad u(0) = u_0.$$

Theorem 1

Let $\alpha \in (\frac{1}{2}, \frac{2}{3})$ and $\vartheta := \frac{9}{2-3\alpha}$ and $\delta := (2\vartheta + 2)\kappa \leq 1$. For any $T > 0$, (b, f) as above, $\exists!$ paracontrolled solution (u, u^\sharp) to PDE (5) such that $\|u\|_{C_T \mathbf{C}_T^{2-\alpha}(\rho_\delta)} + \|u^\sharp\|_{C_T \mathbf{C}_T^{3-2\alpha}(\rho_{2\delta})} \lesssim C(b, f)$.

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difficulty: Loss of weight from $b \cdot \nabla_v u$

Solution from [Zhang, Zhu, Z. 20]:

Step 1: Schauder estimate for b, f in **unweighted** Besov space

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- Uniqueness: Localization

Nonlinear equation

Nonlinear mean field equation

- Assume that $\operatorname{div}_v b = 0$. Consider the following

$$\mathcal{L}u = b \cdot \nabla_v u + K * \langle u \rangle \cdot \nabla_v u, \quad u(0) = u_0. \quad (7)$$

Here $\langle u \rangle(t, x) := \int_{\mathbb{R}^d} u(t, x, v) dv$. Assume that

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$$K \in \cup_{\beta > \alpha - 1} \mathbf{C}_x^{\beta/3}, \quad b \circ \nabla_v \mathcal{I}(b) \in \mathbf{C}_a^{1-2\alpha}(\rho_\kappa)$$

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- for any probability density $u_0 \in L^1(\rho_0) \cap \mathbf{C}_a^\gamma$, $\gamma > 1 + \alpha$, \exists at least a **probability density** paracontrolled solution $u \in L_T^\infty(\mathbf{C}^{2-\alpha}(\rho_\delta))$ to (7).
- If in addition that K is bounded and $H(u_0) := \int u_0 \ln u_0 < \infty$, the solution is unique.

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$$0 = Ew^t(t, Z_t^z) = w^t(0, z) + E \int_0^t (B \cdot \nabla_v \rho_0)(s, Z_s^z) ds.$$

Here w^t is the unique solution of the following backward PDE:

$$\partial_s w^t + (\Delta_v + v \cdot \nabla_x + B \cdot \nabla_v) w^t = B \cdot \nabla_v \rho_0, \quad w^t(t) = 0.$$

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$$\partial_t w = \Delta_v w + v \cdot \nabla_x w + b \cdot \nabla_v w + K * \langle w \rangle \cdot \nabla_v u_1.$$

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\Rightarrow Linear approximation

$$\mathcal{L}u^n = b^n \cdot \nabla_v u^n + K^n * \langle u_1 \rangle \cdot \nabla_v u^n.$$

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- Consider the following kinetic DDSDE with singular drift: $Z = (X, V)$

$$dX_t = V_t dt, \quad dV_t = b(X_t, V_t) dt + (K * \mu_{X_t})(X_t) dt + \sqrt{2} dB_t, \quad (8)$$

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see also [Delarue, Diel 16, Cannizzaro, Chouk 18, Kremp, Perkowski 20]

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Definition 4.1

(Martingale problem) Let $\delta > 0$. A probability measure $\mathbb{P} \in \mathcal{P}(C_T)$ is called a martingale solution to SDE (8), if for all $f \in C_b$, $\varphi \in \mathbf{C}_a^\gamma$ with some $\gamma > 1 + \alpha$ and $\mu_t := \mathbb{P} \circ X_t^{-1}$,

$$M_t := u_f^\mu(t, Z_t) - u_f^\mu(0, Z_0) - \int_0^t f(s, Z_s) ds$$

is a martingale under \mathbb{P} . Here u_f^μ is a solution to (9).

Main results

Theorem 3

Suppose that $b \circ \nabla_v \mathcal{F}(b) \in \mathbf{C}_a^{1-2\alpha}(\rho_\kappa)$ and $K \in \cup_{\beta > \alpha-1} \mathbf{C}_a^\beta$. Then there exists at least one martingale solution \mathbb{P} to SDE (8). Moreover, if K is bounded measurable, then the solution is unique.

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Idea of proof

- Existence: convolution approximation
- Uniqueness: First for $K = 0$ and Girsanov's transformation

Thank you !