

# Traces and higher structures

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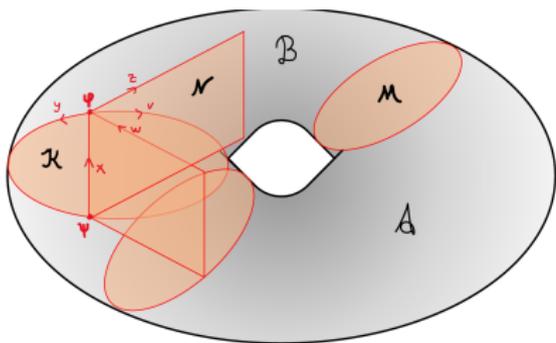
Based on work with  
Julian Farnsteiner, Jürgen Fuchs and Gregor Schaumann

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# Chapter 3

## State-sum models with defects

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Closed oriented 3-manifold with skeleton

$\mathcal{A}, \mathcal{B}$  spherical fusion categories

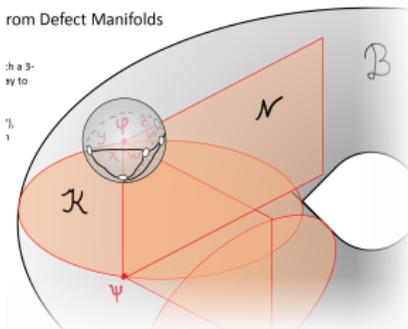
$\mathcal{M}, \mathcal{N}$  bimodule categories

Edges: balanced Deligne products

from Defect Manifolds

is a 3-  
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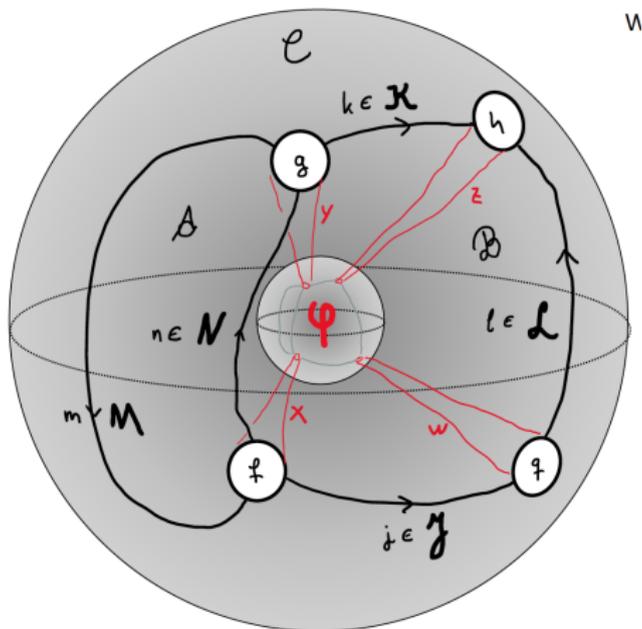


Part of the TV construction is an evaluation at vertices

# Chapter 4

## Extruded graphs

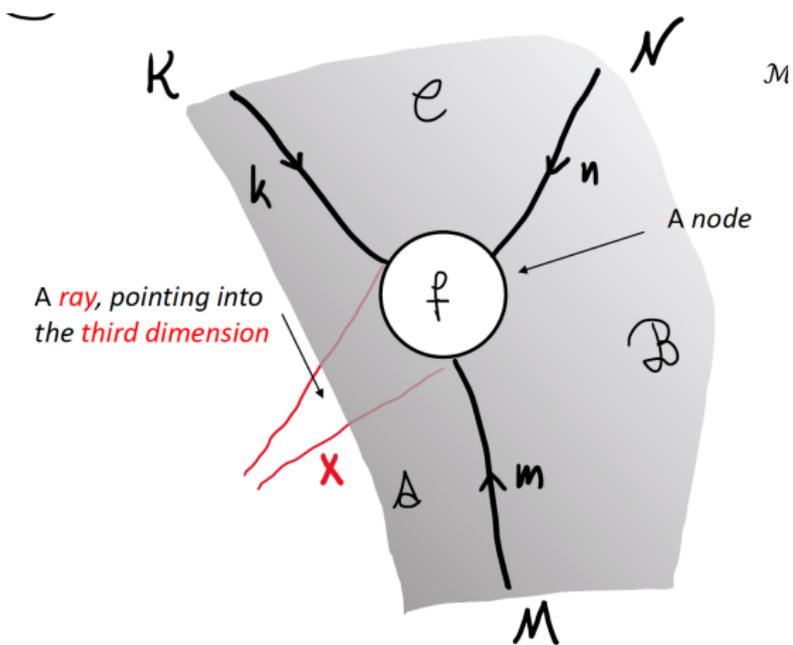
## Extruded graphs



Artin, Theory of braids (1947):

Projection [...] which is an excellent tool for intuitive investigations is a very clumsy one for proofs. This has led me to abandon projections altogether.

## Node labels



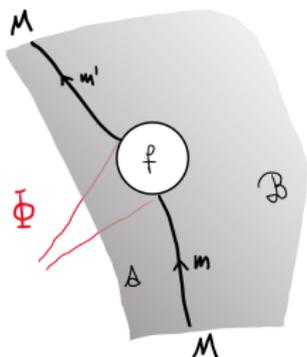
A ray, pointing into the *third dimension*

$$x \in \mathcal{M} \boxtimes_B \mathcal{N} \boxtimes_C \mathcal{K} \boxtimes_A$$

$$U(x) \in \mathcal{M} \boxtimes \mathcal{N} \boxtimes \mathcal{K}$$

$$f : m \boxtimes n \boxtimes n \boxtimes k \rightarrow U(x)$$

## Sanity check: silent rays



$$U(\Phi) = \bigoplus_{\mu} \mu \boxtimes \bar{\mu}$$

$$\text{Hom}_{\mathcal{M} \boxtimes \bar{\mathcal{M}}}(m \boxtimes \bar{m}', \bigoplus_{\mu} \mu \boxtimes \bar{\mu})$$

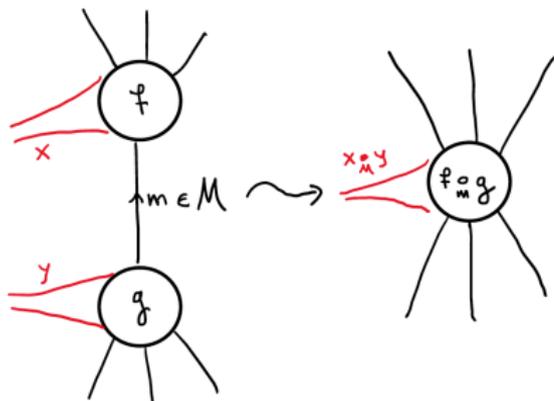
$$= \bigoplus_{\mu} \text{Hom}_{\mathcal{M}}(m, \mu) \otimes \text{Hom}_{\mathcal{M}}(\mu, m')$$

$$= \text{Hom}_{\mathcal{M}}(m, m')$$

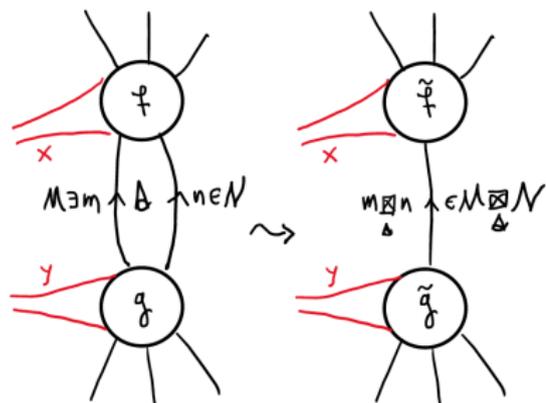


## Local moves

The contraction move



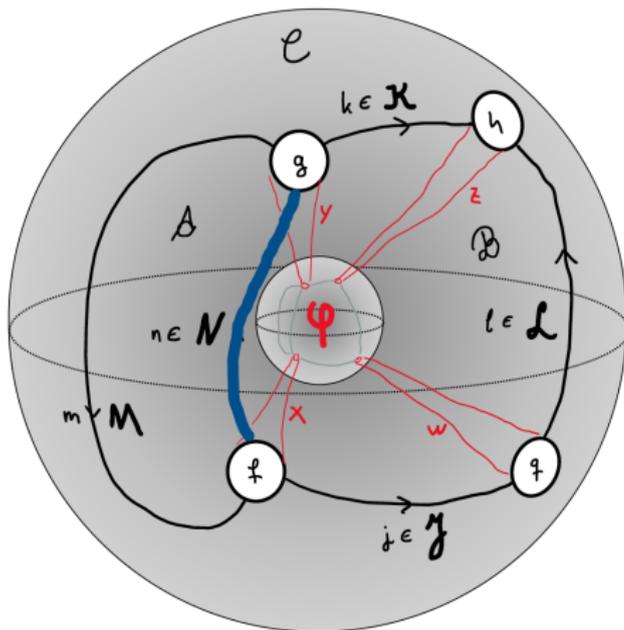
The edge fusion move



**Theorem:** Performing these changes locally in an extruded graph leaves the evaluation invariant.

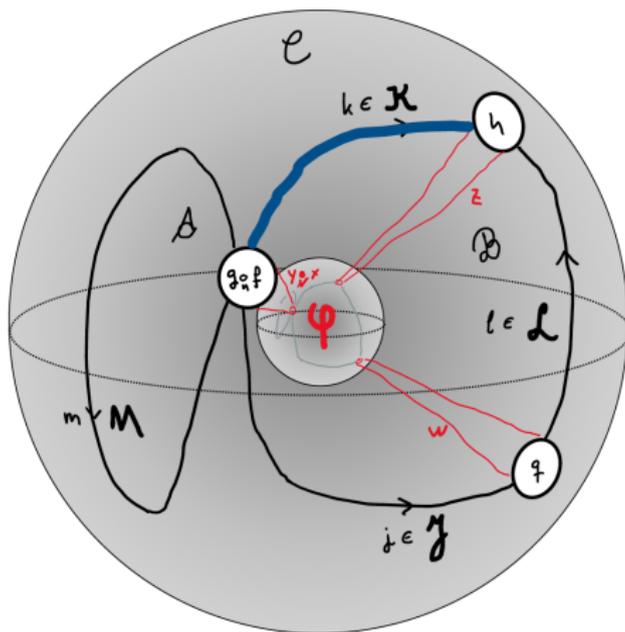
# Example for an evaluation

Simplifying extruded graphs using moves



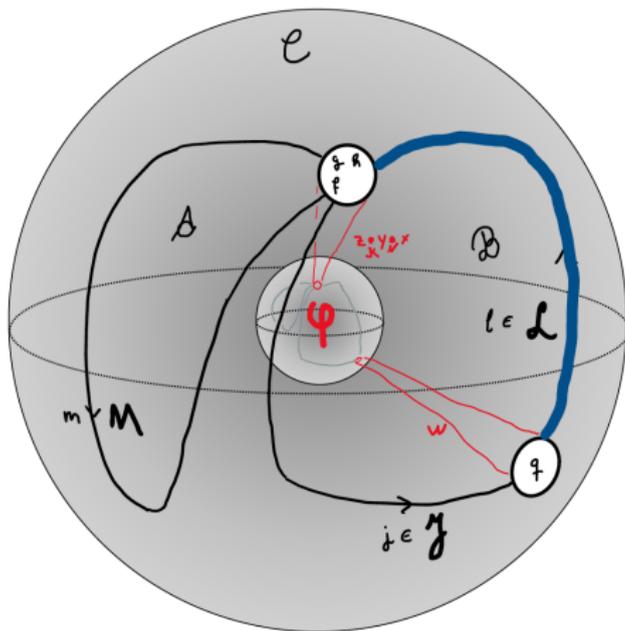
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Simplifying extruded graphs using moves



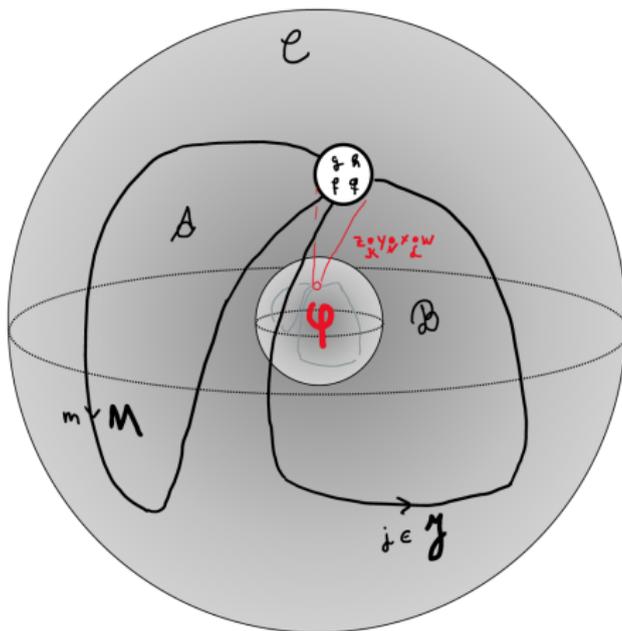
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