Ergodic Properties of a Simple Deterministic Traffic Flow Model Re(al)visited

Michael Blank


Supported by the Austrian Federal Ministry of Education, Science and Culture
Available via http://www.esi.ac.at
Ergodic properties of a simple deterministic traffic flow model re(al)visited

Michael Blank*†

June, 2002

Abstract. We study statistical properties of a family of maps acting in the space of integer valued sequences, which model dynamics of simple deterministic traffic flows. We obtain asymptotic (as time goes to infinity) properties of trajectories of those maps corresponding to arbitrary initial configurations in terms of statistics of densities of various patterns and describe weak attractors of these systems and the rate of convergence to them. Previously only the so called regular initial configurations (having a density with only finite fluctuations of partial sums around it) in the case of a slow particles model (with the maximal velocity 1) have been studied rigorously. Applying ideas borrowed from substitution dynamics we are able to reduce the analysis of the traffic flow models corresponding to the multi-lane traffic and to the flow with fast particles (with velocities greater than 1) to the simplest case of the flow with the one-lane traffic and slow particles, where the crucial technical step is the derivation of the exact life-time for a given cluster of particles. Applications to the optimal redirection of the multi-lane traffic flow are discussed as well.

Keywords: dynamical system, traffic flow, substitution dynamics, attractor, rate of convergence, large deviations.

AMS Subject Classification: Primary 37A60; Secondary 37B15, 37A50, 60K35.

1 Introduction

Let $X_M := \{ x = (x_0, x_1, x_2, \ldots) : x_i \in \mathcal{A}, \ i \in \mathbb{Z} \}$ be the space of bi-infinite sequences (which we also call configurations) from the alphabet $\mathcal{A} = \{0, 1, 2, \ldots, M\}$. We equip this space with the metric

$$\text{dist}_M(x, y) := \sum_{i=-\infty}^{\infty} (M + 1)^{-|i|} |x_i - y_i|$$

and consider a map $T_{1,M} : X_M \to X_M$ from this metric space into itself:

$$(T_{1,M}x)_i := x_i + \min \{x_{i-1}, M - x_i\} - \min \{x_i, M - x_{i+1}\}. \quad (1.1)$$

One can interpret the $i$-th coordinate of $x \in X_M$ as $x_i$ particles and $M - x_i$ holes (empty places) located at the site $i$ of the integer lattice $\mathbb{Z}$. Then this map can be considered as a discrete time / discrete space model for multi-lane highway traffic when a particle (vehicle) at site $i$ of the lane $j$ can switch to any other lane $j'$ (nonnecessary neighboring) whenever it does not disrupt

*Russian Academy of Sci., Inst. for Information Transm. Problems, and Observatoire de la Cote d’Azur, e-mail: blank@itp.ru
†This research has been partially supported by RFFI and CRDF grants and a part of it has been done during my stay at ESI (May, 2002).
point of view of probability theory the dynamics of this map is a deterministic version of an asymmetric exclusion process, i.e. the motion of a collection of random walkers constrained to the nonintersection assumption (see e.g. [9, 6]). Traffic flow phenomena have attracted considerable interest during last decade both from the applied and theoretical points of view. For the general account on these matters we refer the reader to recent reviews [8, 4] (and numerous references cited there) and in this paper we shall concentrate only on the mathematical background of deterministic models of traffic flows.

We shall refer to the system $(T_{1,M}, X_M)$ as the slow particles model, and to take into account traffic flows where particles can move with the (maximal) velocity $v > 1$ (a fast particles model) we consider a family of maps $T_{v,M} : X_M \rightarrow X_M$ describing the $M$-lane traffic flow model with the maximal velocity $|v|$, i.e. a particle in this flow can move to the right (left if $v < 0$) by at most $|v|$ positions if those positions are not occupied.

To simplify the notation we shall drop the indices if they are equal to 1, i.e. $T_2$ means the case $v = 2, M = 1$ and $T_{1,3}$ means the case $v = 1, M = 3$, while $T$ stands for the case $v = M = 1$.

By a dual configuration for the configuration $x \in X_M$ we mean a configuration $x^* \in X_M$ such that $x^*_i = M - x_i$; the operation of taking a dual can be applied also to the map by means of the relation: $T_{v,M}{x^*} = (T_{v,M}x)^* \forall x \in X_M$.

To illustrate the usage of the dual operation consider the slow particles model with ‘smart drivers’, who anticipating the motion of at most $m$ cars ahead, may move to an occupied site ahead of it with the maximal velocity 1. Example for the case $m = 2$: \{011100\} $\rightarrow$ \{010111\}, where \{\cdot\} denotes the main period of a (space) periodic configuration. It is straightforward to show that this model is described by the map $T x = (T_{m,1}x)^* = T_{m,1}^* x$.

By a word $A$ we shall call any (finite or infinite) sequence of elements $a_i \in A_M$ and introduce the notion of the density of a finite word $A$ in a finite word $B$ as

$$
\rho(B, A) := \frac{1}{|B|} \sum_{i=1}^{|B|} \min_{j=1}^{|A|} \left\lfloor \frac{B_{i-1+j}}{A_j} \right\rfloor,
$$

(1.2)

where $|A|$ is the length of the word $A$, $A_j \in A_M$ is the $j$-th element of the word $A$, $|a|$ is the integer part of the number $a$, and we set $0/0 = 1$ here and in the sequel. In the case $M = 1$ the number $\rho(A, B) \in [0, 1]$ and is equal to the number of occurrences of the subword $B$ in $A$ divided by the length of $A$, while in the general case $M > 1$ we have $\rho(A, B) \in [0, M]$ and the formula (1.2) takes into account multiplicities of those occurrences. Example: $\rho(255, 12) = \frac{1}{3}(2+2) = 4/3$.

The generalization of this notion for an infinite word/configuration $x \in X_M$ leads to the notion of lower/upper density.

$$
\rho_{\pm}(x, A) := \lim_{n,m \to \infty} \left( \sup_{n,m} \rho(x[-n, m], A) \right),
$$

where (and in the sequel) $\lim_{n,m \to \infty}$ corresponds to the index $+$ and $\lim_{n,m \to \infty}$ to the index $-$, and $x[n, m]$ a subword of the word $x$ which starts from the position $n$ and goes till the position $m$ in the original word. The asymmetry with respect to $n$ and $m$ is necessary to take into account the possibility to have left and right ‘tails’ with different statistics: for $x := \ldots0001111\ldots$ we have $\rho_{-}(x, 1) = 0$ and $\rho_{+}(x, 1) = 1$, while $\rho(x[-n, n], B) \frac{n+2}{2} 1/2$. Observe also that for a (space) periodic configuration $\langle A \rangle := \ldots AAA\ldots$ we have $\rho_{-}(\langle A \rangle, B) = \rho_{+}(\langle A \rangle, B) = \rho(\langle A \rangle, B)$ for any pair of finite words $A, B$.

For a system of particles on a lattice one can define its average velocity as follows. First, for each particle in a configuration $x \in X$ we define its ‘local’ velocity as a distance by which it will move on the next step of the dynamics:

$$
V(x, i) := \min \{v, 0, \min_{j > i} (i - j, x_j = 1)\},
$$


Figure 1: Fundamental diagram for $T_{v,M}$: dependence of the average velocity $V$ or the flux $\Phi$ on the density $\rho = \rho(\cdot, 1)$.

and, since for $M > 1$ a site $i$ in the configuration $x \in X_M$ may contain several particles (i.e. $x_i > 1$), we sum up their velocities to get $V(x, i)$. For example, in the case of the map $T_{1,M}$ we have $V(x, i) := \min\{x_i, M - x_{i+1}\}$. Note that the ‘local’ velocity is well defined for each site $i$ of a configuration $x \in X_M$ (independently on the presence of a particle there), indeed, if $x_i = 0$ (i.e. there is no particle at this site) we have $V(x, i) = 0$. Now we define the lower/upper average velocity as

$$V_{\pm}(x) := \lim_{n,m \rightarrow \infty} \left( \sup_{\inf} \frac{1}{\rho(x[-n,m], 1) \cdot (n + m + 1)} \sum_{i=-n}^{m} V(x, i) \right).$$

Often it is more suitable to work with another statistics, called flux, equal to the number of particles crossing a given position on the lattice per unit time, i.e. $\Phi(x[-n,m]) := \frac{1}{n+m+1} \sum_{i=-n}^{m} V(x, i)$. Thus we define the upper/lower average flux as

$$\Phi_{\pm}(x) := \lim_{n,m \rightarrow \infty} \left( \sup_{\inf} \frac{1}{n + m + 1} \sum_{i=-n}^{m} V(x, i) \right).$$

We shall use also the notation $\Phi^{(v)}_{\pm}$ to indicate the maximum velocity if needed, and $0_i := 00\ldots0_i$.

The connection of the flux to the densities is given by the following simple result.

**Lemma 1.1** $\Phi^{(v)}_{\pm}(x) = \sum_{i=1}^{v} \rho_{\pm}(x, 10_i)$ for $x \in X$, in particular $\Phi_{\pm}^{(1)}(x) := \rho_{\pm}(x, 10)$.

**Proof.** By definition we have

$$\Phi_{\pm}^{(v)}(x) = v \cdot \rho_{\pm}(x, 10_v) + (v-1) \cdot (\rho_{\pm}(x, 10_{v-1}) - \rho_{\pm}(x, 10_v)) + \ldots + 1 \cdot \rho_{\pm}(x, 10)$$

$$= (v - (v - 1)) \cdot \rho_{\pm}(x, 10_v) + ((v - 1) - (v - 2)) \rho_{\pm}(x, 10_{v-1}) + \ldots + 1 \cdot \rho_{\pm}(x, 10)$$

$$= \sum_{i=1}^{v} \rho_{\pm}(x, 10_i).$$

$\square$

The main results of the paper are the following statements.

**Theorem 1.1** (Invariance of densities) $\rho_{\pm}(T_{v,M}^t x, A) = \rho_{\pm}(x, A)$ for all $x \in X_M$ and $t \in \mathbb{Z}_+$ if and only if $A \in \{0, 1\}$.

Denote by Free$_v := \{x \in X_M : V(x, i) = v \cdot x_i \ \forall i \in \mathbb{Z}\}$ the subset of configurations where all particles have the maximal available velocity and thus move independently. Clearly, $T_{v,M}(\text{Free}_v) = \text{Free}_v$ and $T_{v,M}(\text{Free}_v^*) = \text{Free}_v^*$. It is of interest that Free $\cap$ Free$^* = \emptyset$.  

3
the dynamical system \((T_{v,M}, X_M)\), and for \(x \in X_M\) we have \(T_{v,M}^n x \xrightarrow{\text{Free}_v} \begin{cases} \text{Free}_v & \text{if } \rho_{+}(x,1) \leq \frac{M}{v+1} \\ \text{Free}^* & \text{if } \rho_{-}(x,1) \geq \frac{M}{v+1} \end{cases} \).

**Theorem 1.3** (Limit flux) \(\Phi_{\pm}^1(T_{v,M}^n x) \xrightarrow{n \to \infty} F_{v,M}(\rho_+(x,1))\), where \(F_{v,M}(\xi) := \begin{cases} v \xi & \text{if } \xi \leq \frac{M}{v+1} \\ M - \xi & \text{otherwise} \end{cases} \).

Denote by \(\mu_p\) a product (Bernoulli) measure with the density \(pM\) on the space of sequences \(X_M\).

**Theorem 1.4** (Typical dynamics) For \(\mu_p\)-a.a. \(x \in X_M\) we have \(\rho(x,1) = pM\) and \(\text{dist}_M(T_{v,M}^n x, \text{Free} \cup \text{Free}^*) \leq M^{-1/\gamma+1}\) and \(\limsup_{n \to \infty} \frac{1}{2^n} \sum_{i=-n}^{n} V(T_{v,M}^n x,1) = F_{v,M}(\rho(x,1))\) for any \(\gamma \in (0, 1)\).

In this result one can use instead of \(\mu_p\) any probabilistic translation invariant measure with fast enough decay of correlations (see Lemma 2.11).

Proofs of Theorems 1.1-1.4 are based on the reduction of the general case \(v, M \geq 1\) to the simplest one \(v = M = 1\). For \(v = 1, M > 1\) this reduction boils down to the proof that a multi lane traffic flow can be represented by a direct product of one-lane flows (see Theorem 4.1 describing the ‘sawtooth redirection’ construction). In the case \(v > 1, M = 1\) we make use of a specially constructed substitution dynamics (see Lemma 3.1) to prove the reduction, while in the general case \(v, M > 1\) we combine these two arguments. The main technical step of the analysis in the case \(v = M = 1\) is the derivation of the exact life-time for a given cluster of particles, i.e. the number of iterations after which it will disappear, described in Lemma 2.4. Note that earlier only very weak (and unnaturally large) estimates of the life-time type were known (see, e.g. [2, 3, 7]).

We provide also the analysis of the rate of convergence to the limit of various statistics for space periodic, regular, and ‘typical’ initial configurations based on large deviations estimates (see Section 5), and study the dynamics of a passive tracer in the flow of fast particles (Section 7).

It is clear that the main problem in the study of traffic flows is the analysis of ‘traffic jams’ (without them the dynamics is trivial): we shall say that a segment \([n, m]\) with \(m > n\) corresponds to the jammed cluster if \(\max\{V(x,i)/x_i : n \leq i < m\} < v\) and \(V(x,n-v)/x_{n-v} = V(x,m)/x_m = v\), i.e. all particles inside of this segment do not have the maximum available velocity. Note that in the case \(v = M = 1\) the jammed cluster is the same as the cluster of particles.

## 2 Dynamics of slow particles \((T, X)\)

This model has been introduced originally in [11] for the case of a traffic flow on a finite lattice (say of size \(L\)) with periodic boundary conditions and studied numerically in a large number of publications. It is straightforward to show that this case corresponds to the restriction of the map \(T\) to (space) \(L\)-periodic configurations. The first ‘quasi-analytic’ result for the \(L\)-periodic case has been obtained in [7] for ‘typical’ initial configurations of length \(L\). However the first complete proof appeared only in [2], where regular initial configurations on the infinite lattice were considered as well. In this section we shall study the problem for all initial configurations, using a rather different and more simple approach than the one in [2].

Let us start from the analysis of lower and upper densities. Note that if the lower density coincides with the upper one, i.e. the limit value exists, we call this common value the density \(\rho(\cdot, \cdot)\). Example when they do not coincide: \(1 = \rho_{+}(\ldots 111000 \ldots, 1) \neq \rho_{-}(\ldots 111000 \ldots, 1) = 0\).

**Lemma 2.1** \(\rho_{\pm}(x,1) = 1 - \rho_{\mp}(x,0)\), and thus \(\rho_{\pm}(x^*, 1) = 1 - \rho_{\mp}(x, 1)\).
\[
\rho_-(x, 1) = \liminf_{n,m \to \infty} \rho(x[-n, m], 1) = 1 - \limsup_{n,m \to \infty} \rho(x[-n, m], 0) = 1 - \rho_+(x, 0),
\]

since \(\rho(A, 1) \cdot |A| + \rho(A, 0) \cdot |A| = |A|\) for any finite binary word \(A\). The derivation for the upper density follows the same argument, while the second statement follows from the identity:

\[
\rho(x^*[-n, m], 1) = \rho(x[-n, m], 0) = 1 - \rho(x[-n, m], 1).
\]

\(\square\)

**Lemma 2.2** \(\rho_+(x, A) \geq \rho_+(x, B) \cdot \rho(B, A)\) for any configuration \(x \in X\) and any pair of finite words \(A, B\).

**Proof.** If \(A \not\subseteq B\) the inequality becomes trivial, since \(\rho(B, A) = 0\), while \(\rho_+(x, A) \geq 0\). Assume now that \(A \subseteq B\). Then \(\forall n, m \in \mathbb{Z}\) we have \(\rho(x[-n, m], A) \geq \rho(x[-n, m], B) \cdot \rho(B, A)\) because the right hand side takes into account only those enclosures of \(B\) to \(x\) when the word \(B\) belongs to a segment \(x[i, j] = A\), while there might be other enclosures as well. \(\square\)

**Proof** of Theorem 1.1 in the case \(v = M = 1\). Let us prove first that \(\rho_+(x, 1) = \rho_+(T x, 1)\) for all \(x \in X\). For any \(n, m \in \mathbb{Z}_+\) we have \(\left| \sum_{i=-n}^{m} (x_i; - (T x)_i) \right| \leq 2\), since during one iteration of the map at most one particle can enter the interval of sites from \(-n\) to \(m\) (from behind) and at most one particle can leave this interval.

By the definition of the lower density there is a sequence of pairs \((n_j, m_j) \xrightarrow{j \to \infty} (\infty, \infty)\) such that

\[
\frac{1}{n_j + m_j + 1} \sum_{i=-n_j}^{m_j} x_i \xrightarrow{j \to \infty} \rho_-(x, 1).
\]

On the other hand, since \(\left| \sum_{i=-n_j}^{m_j} x_i - \sum_{i=-n_j}^{m_j} (T x)_i \right| \leq 2\), we deduce that \(\rho_-(x, 1)\) is a limit point for partial sums for the sequence \(T x\). Therefore we need to show only that this is indeed the lower limit. Assume, on the contrary, that there is another limit point, call it \(\xi\), for the partial sums for \(T x\) such that \(\xi < \rho_-(x, 1)\). Doing the same operations with the partial sums for \(T x\) converging to \(\xi\) we can show that this value is also a limit point for the partial sums for the sequence \(x\), and, hence, \(\xi\) cannot be smaller than \(\rho_-(x, 1)\).

The proof for the upper density follows from the similar argument.

By Lemma 2.1 we have \(\rho_+(x, 1) = 1 - \rho_+(x, 0)\), which proves the preservation of the density of zeros as well.

To prove that all other statistics are not preserved under dynamics we need to study it in more detail. Therefore we postpone the continuation of the proof till the end of this Section.

**Lemma 2.3** \(T^* = T_{-1}\).

**Proof.** The action of the map \(T\) on binary configuration is equivalent to the exchange of any pair 10 to 01. Since the dual map describes the dynamics of holes it corresponds in this case to the exchange of pairs 01 to 10, which proves the statement. \(\square\)

By a cluster (of particles) in a binary configuration \(x \in X\) we mean a collection of consecutive positions \(x_m, x_{m+1}, \ldots, x_n\) such that \(n - m > 1, x_i = 0 \forall i \in (m, \ldots, n)\) and \(x_{m-1} = x_{n+1} = 0\). After each iteration of the map \(T\) the last particle in the cluster moves away (i.e., \((Tx)_n = 0\)) and either appears a new element in the cluster from the left (i.e., \((Tx)_{m+1} = 1\) and \((Tx)_{m-1} = 0\)), or the first particle preserves its position \(m\). Therefore the number of particles in a given cluster cannot increase, and the time up to the moment when the cluster length shrinks to 1 (i.e. it
Define an integer-valued function
\[ I(x, i) := \max \{ k < i : \rho(x[k, i], 1) = \rho(x[k, i], 0) \}. \] (2.1)

**Lemma 2.4** Let \( \sum_{i=m}^{n} x_i = n - m + 1 \) (i.e. the positions from \( m \) to \( n \) correspond to a cluster of particles and let \( I(x, n) = -\infty \), then after exactly \( \frac{1}{2} (n - I(x, n) - 1) \) iterations (which is equal to the number of ones minus one in the word \( x[n - I(x, n), n] \)) this cluster will disappear. If \( \rho_+(x) \leq 1/2 \) then \( \forall i \in \mathbb{Z} \) we have \( I(x, i) > -\infty \).

**Proof.** Let \( \Omega^{2n} := \{ A \in \{0, 1\}^{2n} : A_{2n} = 1, I(A, 2n) = 1 \} \), where \( I(x, i) \) is defined by the relation (2.1) and thus \( \rho(A, 1) = |A|/2 \). Observe that if \( A \in \Omega^{2n} \) then for any \( 0 < m < n \) and any word \( B \in \{0, 1\}^{2m} \) such that \( B_i = A_i \forall 0 < i \leq 2m \) we have \( B \not\in \Omega^{2m} \). Therefore we shall call the words from \( \Omega^{2n} \) **minimal** words (or minimal intervals) corresponding to clusters of particles in their ends.

Consider a map \( \Gamma : \Omega^{2n} \to \mathbb{Z}^{2n-2} \) defined by the relation:
\[ (\Gamma A)_{i+1} = A_i + \min \{ A_{i-1}, 1 - A_i \} - \min \{ A_i, 1 - A_{i+1} \}. \]
Observe that this is a shift to the right of the action of our map \( T \). We shall prove that for each \( n \) we have \( \Gamma : \Omega^{2n} \to \Omega^{2n-2} \).

\[
\begin{align*}
A &= 0 \quad 0 \quad 0 \quad 1 \quad 0 \quad 1 \quad 1 \quad 0 \quad 1 \quad 0 \quad 0 \quad 1 \quad 1 \\
\Gamma^1 A &= 0 \quad 0 \quad 0 \quad 1 \quad 0 \quad 1 \quad 1 \quad 0 \quad 0 \quad 1 \quad 0 \quad 1 \quad 1 \\
\Gamma^2 A &= 0 \quad 0 \quad 1 \quad 0 \quad 1 \quad 1 \quad 0 \quad 0 \quad 1 \quad 1 \\
\Gamma^3 A &= 0 \quad 0 \quad 1 \quad 1 \\
\Gamma^4 A &= 0 \quad 1 \\
\end{align*}
\]
Examples of the action of \( \Gamma^i \) on \( \Omega^{10} \) (left) and \( \Omega^{8} \) (right).

Let \( A \in \Omega^{2n} \) and let \( \zeta_A \) be the position of the last 0 in \( A \). For each word \( A \in \Omega^{2n} \) define a new word \( A' \in \mathbb{Z}^{2n-2} \) as follows:
\[ A'_i := \begin{cases} 
A_i & \text{if } i \leq 2n - 2 \text{ and } i \neq \zeta_A \\
1 & \text{if } i = \zeta_A.
\end{cases} \]

Then \( |A'| = |A| - 2 = 2n - 2 \), \( \rho(A', 1) = 1/2 \) and thus \( A' \in \Omega^{2n-2} \) since otherwise \( A \) would be not minimal as well. Now using the following simple identity:
\[ (\Gamma A)_i = \begin{cases} 
(\Gamma A')_i & \text{if } \zeta_A - i \not\in \{1, 2\} \\
0 & \text{if } i = \zeta_A - 2 \\
A_{\zeta_A} & \text{if } i = \zeta_A - 1 \\
1 & \text{if } i = |A| - 2,
\end{cases} \]
we get \( \Gamma A \in \Omega^{2n-2} \). Example: \( A = 001011, A' = 0011 \).

It remains to show that if we have a cluster of particles located in the end of a minimal configuration \( A \in \Omega^{2n} \) then this cluster (i.e. particles at sites from \( \zeta_A + 1 \) to \( 2n \)) will vanish after \( n - 1 \) iterations. Observe that after one iteration of the map \( T \) the cluster either preserves its length, or the length decreases by one (when two positions immediately preceding the cluster are occupied by two zeros). The map \( \Gamma \) defined above controls this process since for each \( A \in \Omega^{2n} \) and each \( 0 \leq t \leq n - 1 \) the last positions starting from \( (\zeta_{\Gamma^t A} + 1) \) correspond to the cluster under study. \( \square \)
Lemma 2.6 Let \( A := x[n, m] \) and \( A' := x[n', m'] \) be two minimal words in the configuration \( x \in X \). Then the inequality \( m < m' \) yields either \( m < n' \) (i.e. \( A \cap A' = \emptyset \)), or \( n' < n \) (i.e. \( A \subset A' \)).

Proof. Assume on the contrary that \( n \leq n' \leq m \). Then by the definition of a minimal word we have
\[
\frac{1}{2} (m' - n' + 1) = \rho(x[n', m'], 1) \cdot (m' - n' + 1) \\
= \rho(x[n', m], 1) \cdot (m - n' + 1) + \rho(x[m, m'], 1) \cdot (m' - m + 1) \\
> \frac{1}{2} (m - n' + 1 + m' - m + 1) = \frac{1}{2} (m' - n'+ 2).
\]
We came to a contradiction. \( \square \)

Corollary 2.7 For a given particle \( \xi \) in a configuration \( x \in X \) let the length of the largest minimal word to which \( \xi \) belongs be \( 2n \). Then for any \( t \geq n - 1 \) the local velocity of the particle \( \xi \) in the configuration \( T^i x \) is equal to 1.

Observe that in the case \( v = M = 1 \) the set Free = \( \{ x \in X_1 : x_i x_{i+1} = 0 \ \forall i \} \) and is the union of ‘free’ particles (i.e. particles having velocity 1), while its dual Free* = \( \{ x \in X_1 : (1 - x_i)(1 - x_{i+1}) = 0 \ \forall i \} \) corresponds to ‘free’ holes (i.e. to holes having velocity -1).

Lemma 2.8 Let \( \rho_+(x, 1) \leq 1/2 \), then each cluster of particles in the configuration \( x \) will disappear after a finite number of iterations and \( \text{dist}(T^n x, \text{Free}) \to 0 \). If there is a cluster of particles having an infinite minimal word (i.e. which does not vanish in finite time), then \( \rho_+(x, 1) > 1/2 \). If \( \rho_+(x, 1) > 1/2 \) then there are clusters of particles with arbitrary large (but may be finite) minimal words.

Proof. Let \( x \in X \) satisfies the assumption that \( \rho_+(x, 1) \leq 1/2 \) and let the segment \( x[n, m] \) be a cluster of particles. Then there exist a pair of integers \( n', m' \) such that \( \inf y < n' < n < m < m' \leq m < \infty \) and \( x[n', m'] \) is the largest minimal word covering the cluster of particles \( x[n, m] \) (otherwise this would contradict to the definition of the upper density). Hence by Lemma 2.4 after at most \( (m' - n')/2 \) iterations this cluster will disappear and all particles will become free. Since this argument can be applied to any cluster of particles, this yields the first statement.

Assume now that the minimal word of a cluster of particles \( x[n, m] \) is not bounded. Then for any \( n' < n \) we have \( x[n', m] > 1/2 \) and thus for any \( k \in \mathbb{Z}_+ \) we have
\[
\rho(x[n - k^2, m + k], 1) \geq \frac{m + k - n + k^2 + 1}{m - n + k^2 + 1} \rho(x[n - k^2, m], 1) \\
> \frac{m - n + k^2 + 1}{m + k - n + k^2 + 1} \cdot \frac{1}{2} = \left( 1 - \frac{k}{m + k - n + k^2 + 1} \right) \cdot \frac{1}{2} \to 0.
\]
Therefore \( \rho_+(x, 1) > 1/2 \), which proves the second statement.

The last statement is an immediate consequence of the definition of the minimal word. \( \square \)
Proof. By Lemma 2.1 we have $\rho_+(x^*, 1) = 1 - \rho_-(x, 1) < 1/2$. On the other hand, Lemma 2.3 shows that asymptotic properties of the maps $T$ and $T^*$ coincide, thus we can apply the statements of Lemma 2.8 for the case of $(T^*)^i x^*$ to prove the desired result. $$
abla$$

Note now that there are configurations not satisfying the assumptions of Lemmata 2.9,2.8 which still converge to $\text{Free} \cup \text{Free}^*$ under the action of the map $T$. Indeed, let $y = \ldots 111000 \ldots$ and let the index 0 correspond to the first 0 in $y$. Observe that $\rho_-(y, 1) = 0 < \rho_+(y, 1) = 1$, however $\text{dist}(T^l y, \text{Free}) = 2^{-l(1+1)}(1 + 2^{-2} + 2^{-4} + \ldots) = \frac{2}{3} \cdot 2^{-l} \frac{t \to \infty}{t \to \infty} 0$, since for large $t$ the ‘central’ part of $T^l y$ will be occupied only by free particles. On the other hand, for $y^* = \ldots 000111 \ldots$ we have $\text{dist}(T^l y^*, \text{Free}) = 2^{-1} + 2^{-3} + \ldots + 2^{-2n+1} + \ldots = 1/3$ for each $t \in \mathbb{Z}^+$, while $\text{dist}(T^l y^*, \text{Free}) = \frac{2}{3} \cdot 2^{-l} \frac{t \to \infty}{t \to \infty} 0$.

Lemma 2.10 For any $x \in X$ we have $\text{dist}(T^l x, \text{Free}) \frac{t \to \infty}{t \to \infty} 0$ if and only if $\rho_+(x[1, \infty], 1) \leq 1/2$. If additionally there exist a pair $n, m \in \mathbb{Z}^+$ such that $\rho(x[i, i + m - 1], 1) \leq 1/2$ for each $i \geq n$ we have $\text{dist}(T^l x, \text{Free}) \leq \text{Const}\ 2^{-l}$.

Proof. Observe that $\rho_+(x[1, \infty], 1) \leq 1/2$ implies that there exists $N \in \mathbb{Z}$ such that the life-time for each cluster of particles lying to the right from $N$ is finite. On the other hand, the distance from the most right cluster of particles in $T^l x$ located to the left of $N$ to the position $N$ grows with $t$ linearly. This proves the first statement and shows that the rate of convergence might be smaller than $2^{-l}$ only if the life-time of clusters of particles lying to the right from a sufficiently large position $N$ is not bounded. The additional assumption guarantees that this cannot happen, which yields the second statement. $$
abla$$

Let $\mathcal{M}(X)$ be the set of probabilistic translation invariant measures on $X$ and let $\mu[\phi(x)] := \int \phi(x) d\mu(x)$ for $\mu \in \mathcal{M}(X)$, in particular, $\mu[x_0] := \mu(x \in X : x_0 = 1)$. Consider a subset of $\mathcal{M}(X)$ corresponding to measures in the space of sequences with weak dependence between coordinates (exponentially fast decay of correlations):

$$
\mathcal{M}_p(X) := \{\mu \in \mathcal{M}(X) : \mu[x_0] = p, \text{ } |\mu[x_0 \cdot x_k] - \mu^2[x_0]| \leq Ce^{-a |k|}\},
$$

for some $C, a$ and $\forall k \in \mathbb{Z}$. Note that, e.g., a product (Bernoulli) measure $\mu_p \in \mathcal{M}_p(X)$.

Lemma 2.11 For any $\mu \in \mathcal{M}_p(X)$ we have $\rho(x, 1) = p$ for $\mu$-a.a. $x \in X$, and thus $\mu(x \in X : \rho_-(x) < 1/2 < \rho_+(x)) = 0$.

Proof. Let $S_{n,m}(x) := \sum_{i=n}^{m} x_i$. Then $\mu[S_{n,m}(x)] = p$ and by Chebyshev inequality $\forall \varepsilon > 0$ we have

$$
\mu(x \in X : |S_{n,m}(x) - p| > \varepsilon) \leq \frac{1}{\varepsilon^2} : \mu[(S_{n,m}(x) - p)^2].
$$

A straightforward calculation shows that $\mu[(S_{n,m}(x) - p)^2] \leq \frac{C}{n + m + 1}$ and thus

$$
\mu \left( x \in X : \frac{1}{n + m + 1} \sum_{i=n}^{m} x_i - p \geq \varepsilon \right) \leq \frac{C_1}{(n + m + 1)\varepsilon^2} \xrightarrow{n,m \to \infty} 0.
$$

Therefore $\rho_\pm(x[-n, m], 1) \xrightarrow{n,m \to \infty} p$ in probability, which yields the existence of the density $\rho(x, 1) = p$ for $\mu$-a.a. $x \in X$ and thus the statement under question. $$
abla$$

Denote by $\text{Per}_n(T) := \{x \in X : T^nx = x\}$ the set of $n$-periodic (in time) trajectories of the map $T$ and by $\mathcal{B}(Y) := \cup_{n > 0} T^{-n}Y$ the basin of attraction of a subset $Y \subset X$. 

8
dist(·, ·). For each \( n \in \mathbb{Z}_+ \) there exists an \( n \)-periodic trajectory, and all periodic trajectories are unstable. \( \text{Clos}(\mathcal{B}(\text{Free} \cup \text{Free}^*)) = X \), (\text{Free} \cup \text{Free}*) \cap \text{Per}_1(T) = \emptyset \), and \( \mu_\nu(\mathcal{B}(\text{Per}_1(T))) = 0 \) while \( \text{Clos}(\mathcal{B}(\text{Per}_1(T))) = X \).

**Proof.** Let us start with the Lipschitz continuity. Consider two configurations \( x \neq y \in X \) and assume that \(-n < 0\) is the largest negative index and \( m \geq 0\) is the smallest nonnegative index of sites, where they differ, i.e. for all \(-n < i < m\) we have \( x_i = y_i\). Then we have

\[
dist(x, y) \leq 2^{-n} + 2^{-m}.
\]

On the other hand, a straightforward calculation shows that the closest to the origin from the left side differing coordinates of the configurations \( Tx \) and \( Ty \) belong to the set \((-n+1), -n, -(n-1)\), while the closest from the right side belong to \(\{m-1, m, m+1\}\). Thus

\[
2^{-(n+1)} + 2^{-(m+1)} \leq \dist(Tx, Ty) \leq 2^{-(n-1)} + 2^{-(m-1)}.
\]

Therefore

\[
\frac{1}{4} = \frac{2^{-(n+1)} + 2^{-(m+1)}}{2^{-(n-1)} + 2^{-(m-1)}} \leq \frac{\dist(Tx, Ty)}{\dist(x, y)} \leq \frac{2^{-(n-1)} + 2^{-(m-1)}}{2^{-(n-1)} + 2^{-(m-1)}} = 4.
\]

For a given \( n \in \mathbb{Z}_+ \) consider a space-periodic configuration \( x \in X \) with the (space) period \( n \), e.g. \( x_i = x_{i+n}, \forall i \). Then it is immediate to show that for any \( t \in \mathbb{Z} \) the configuration \( Tx \) is again space periodic with the same period \( n \) and converges either to Free, or to \( \text{Free}^* \), depending on its density. This gives a construction of the \( n \)-periodic (in time) trajectories.

The structure on the set of fixed points \( \text{Per}_1(T) \) is a bit more involved:

\[
\text{Per}_1(T) := \left\{ x^{(n)} \in X : x^{(n)}_i = \begin{cases} 0 & \text{if } i < n \\ 1 & \text{otherwise} \end{cases} \right\}.
\]

Indeed, assume that \( Tx = x \), then either \( x \) does not have zero coordinates, or all coordinates starting from, say, \( n \)-th, should be equal to one. Now for \( x^{(n)} \in \text{Per}_1(T) \) we define \( y^{(n,m)} \in X \) such that

\[
y^{(n,m)}_i = \begin{cases} 0 & \text{if } i < n, \text{ or } i > m \\ 1 & \text{otherwise} \end{cases}
\]

for some \( m > n \). Then \( \dist(x^{(n)}, y^{(n,m)}) = 2^{-m} \xrightarrow{m \to \infty} 0 \), while \( \dist(T^t x^{(n)}, T^t y^{(n,m)}) \xrightarrow{t \to \infty} 2^{-(n-1)} \neq 0 \). Thus for each \( \varepsilon > 0 \) there is configuration \( x' = x'(\varepsilon) \) such that \( \dist(x^{(n)}, x') \leq \varepsilon \) and \( T^t x' \not\to x^{(n)} \) as \( t \to \infty \), which yields instability.

Observe now that the set \( Y := X \setminus (\mathcal{B}(\text{Free} \cup \text{Free}*)) = \{ x \in X : \rho_-(x) < 1/2 < \rho_+(x) \} \) has \( \mu_\nu \)-measure zero, since for each \( \mu_\nu \)-typical trajectory the lower and upper densities coincide.

Consider now an arbitrary configuration \( x \in X \) and a sequence of configurations \( \{y^{(n)}\}_n \) defined as \( y^{(n)}_i = \begin{cases} x_i & \text{if } i < n, \\ 1 & \text{otherwise} \end{cases} \). Then \( \dist(x, y^{(n)}) \leq 2^{-n+1} \), on the other hand, \( y^{(n)} \xrightarrow{n \to \infty} \text{Per}_1(T) \), which proves the last statement. \( \square \)

**Remark.** In the case of a finite cluster of particles its last particle immediately leaves under the dynamics. This is not the case for clusters not bounded from the right, which explains the existence of fixed points.

We shall say that a closed \( T \)-invariant set \( Y \) is a \textit{weak attractor} if \( \mu_\text{ref}(\mathcal{B}(Y)) > 0 \). A weak attractor \( Y \) is called a \textit{Milnor attractor} if \( \mu_\text{ref}(\mathcal{B}(Y) \setminus \mathcal{B}(Y')) > 0 \) for any proper compact invariant subset \( Y' \subseteq Y \) (see, e.g. [10]).
Proof. The sets Free and Free$^*$ are closed, since they contain all their limit points. Let $Z^{(v)} := \{ x \in \text{Free} : \rho(x) = p \}$ - this is an invariant set and $\mu_p(B(Z^{(v)})) = 1$. Denote now by $Z^{(v)}$ a single configuration from $Z^{(v)}$ together with all its left and right shifts. Clearly $\mu_p (Z^{(v)} \setminus (Z^{(v)} \setminus Z^{(v)})) = \mu_p(Z^{(v)}) = 0$. Observe that the points from the complement to the basins of attraction of Free and Free$^*$ are everywhere dense, which proves the absence of included open sets. The last statement follows from the fact that the basin of attraction does not contain any open set. \[ \square \]

Proof of Theorem 1.1 (continuation). Let us prove now that for any word $A$ with $|A| > 1$ the density $\rho(x, A)$ is not preserved under dynamics. There might be 3 possibilities: $\rho(A, 1) < 1/2$, $\rho(A, 1) > 1/2$ and $\rho(A, 1) = 1/2$. We start from the first case. Clearly $\rho(A, 1) < 1/2$ yields $\rho(A, 00) > 0$. Consider a configuration $x := \langle A_{111 \ldots 1} \rangle$, where $x = (B) \equiv \ldots BBB \ldots$ stays for a space-periodic configuration. By the construction $\rho(x, 1) = (\rho(A, 1) \cdot |A| + 2|A|)/(3|A|) \geq 2/3 > 1/2$. Therefore $T^t x \overset{t \to \infty}{\longrightarrow} \text{Free}^*$ and hence $\rho(T^t x, 00) \overset{t \to \infty}{\longrightarrow} 0$. Assume now that the density is preserved, i.e. $\rho(T^t x, A) = \rho(x, A)$ $\forall t$. Then by Lemma 2.2 we have

$$\rho(T^t x, 00) \geq \rho(T^t x, A) \cdot \rho(A, 00) = \rho(x, A) \cdot \rho(A, 00) > 0,$$

while the left hand side vanishes when $t \to \infty$. We came to the contradiction.

If $\rho(A, 1) > 1/2$ we shall follow a similar argument, considering another space-periodic configuration $x := \langle A_{000 \ldots 0} \rangle_{2|A|}$.

In a more delicate case $\rho(A, 1) = 1/2$ we do the following. If additionally $\rho(A, 11) > 0$ we follow the same argument as in the case $\rho(A, 1) < 1/2$ to show that $\rho(x, 11) > 0$, while $\rho(T^t x, 11) \overset{t \to \infty}{\longrightarrow} 0$. If $\rho(A, 00) > 0$ we follow the case $\rho(A, 1) > 1/2$ to show that $\rho(x, 00) > 0$, while $\rho(T^t x, 00) \overset{t \to \infty}{\longrightarrow} 0$. It remains to consider the case when $\rho(x, 11) = \rho(x, 00) = 0$, i.e. $A = 1010 \ldots 10$ or $A = 0101 \ldots 01$. In the first of these cases we choose $x := \langle 1A0 \rangle$. Then

$$\rho(\langle 1A0 \rangle, A) = \lim_{n \to \infty} \frac{n}{n(|A| + 2)} = \frac{1}{|A| + 2} \leq \frac{1}{2} = \lim_{n \to \infty} \frac{n|A|}{n|A|} = \rho(T(\langle 1A0 \rangle), A).$$

In the second case we choose $x := \langle 0A1 \rangle$ to come to a similar contradiction. \[ \square \]

Proof of Theorem 1.2 in the case $v = M = 1$ follows from Lemmata 2.8-2.12. \[ \square \]

Proof of Theorem 1.3 in the case $v = M = 1$. We have the following identity: $\rho_+(x, 1) = \rho_+(x, 10) + \rho_+(x, 11)$. If $\rho_+(x, 1) \leq 1/2$ then $T^t x \rightarrow \text{Free}$ and $\rho_+(T^t x, 11) \to 0$, thus $\Phi_+(T^t x) = \rho_+(T^t x, 10) = \rho_+(T^t x, 1) - \rho_+(T^t x, 11) \to \rho_+(T^t x, 1) = \rho_+(x, 1)$. The situation $\rho_-(x, 1) \geq 1/2$ can be reduced to the previous one by going to the dual configuration.

Consider now the case $\rho-(x, 1) < 1/2 < \rho_+(x, 1)$. By definition there exists a sequence of pairs of positive integers $n_i, m_i \to \infty$ such that $\rho(x[-n_i, m_i], 1) \overset{t \to \infty}{\longrightarrow} \rho_-(x, 1) < 1/2$. For each $i$ we choose integers $n_i \geq n_i', m_i \geq m_i'$ to be the smallest integers satisfying the condition that $-n_i - 1$ is the ending point and $m_i + 1$ is the starting point of some nonoverlapping minimal intervals of the configuration $x$. If there are no more nonoverlapping minimal intervals in the considered direction or the segment $x[-n_i', m_i']$ intersects with an infinitely long minimal interval we set $n_i := n_i'$ or $m_i := m_i'$ respectively, depending on the direction where this event occurs. Clearly,
3 Dynamics of fast particles \((T_v, X)\)

Note that the analysis of dynamics of the slow particles model \((T, X)\) is divided logically into two parts: first, we study low density initial configurations \(x \in X\) with \(\rho_+(x, 1) \leq 1/2\), and then for high density configurations \(x \in X\) with \(\rho_-(x, 1) > 1/2\) we pass to the dual ones using the property that \(\rho_+(x^*, 1) \leq 1 - \rho_-(x, 1) < 1/2\) and argue that the dual map \(T^* \equiv T_{-1}\) has exactly the same asymptotic properties as \(T\). The problem with the fast particles model \((T_v, X)\) is that the dual map \(T_v^* \neq T_{-v}\) in this case, and, in fact, has a very nontrivial dynamics. Namely, \(T_{-v}^*\) corresponds to the situation, known in physical literature (in the case \(v = 2\)) as a traffic model with ‘smart drivers’, who anticipating the motion of at most \(v\) cars ahead, may move to an occupied site ahead of it with the maximal velocity 1. Example for the case \(v = 2\):

\[
(01110) \xrightarrow{T_v} (01011).
\]

Therefore since we are unable to study directly the dual map in this case and according to the entire ideology of this paper, we elaborated a reduction to the main case \(v = M = 1\) based on the following consideration. Note that under the action of the map \(T\) on \(x \in X\) each pair 10 goes to 01 (i.e. the position of a particle and a hole are exchanged). Therefore \(T\) is equivalent to the substitution rule 10 \(\rightarrow\) 01. To apply this idea to the case of \(T_v\) we introduce an alphabet \(A_v := \{0_1, 0_2, \ldots, 0_v, 1\}\) with \(v + 1\) symbols and a map \(C_v : X \rightarrow \mathbb{Z}^v \equiv X_v\) defined as follows: for each segment \(x[i, i + n + 1] = 1 \overbrace{0 \ldots 0}^{n} 1\), we set \(C_v x[i, i + n + 1] := 1 \overbrace{0 \ldots 0}^{[n/v]} 0_0 \ldots 0_v 0_{n-[n/v]} 1\). If \(n - [n/v] v = 0\) we shall drop the last element in \(C_v x[i, i + n + 1]\). It remains to define the action of \(C_v\) on ‘tails’ of \(x\) consisting of only zeros, which we set according to the following rules:

\[
\ldots 0001 \ldots \xrightarrow{C_v} \ldots 0_0 \ldots 0_v 0_1 \ldots \text{ and } \ldots 1000 \ldots \xrightarrow{C_v} \ldots 10_0 \ldots 0_v \ldots .
\]

Now we are ready to define the substitution map \(S_v : X_v \rightarrow X_v\) acting in the set \(X_v\) according to the set of \(v\) substitution rules \(10_i \rightarrow 0_1 0_{i+1}\) for \(0 < i < v\), which generalizes the substitution rule for the slow particles dynamics for the case of \(v\) different types of holes.

To study the life-time of clusters of particles in configurations \(x \in X_v\) we introduce also a new map \(\tilde{T} := C_v C_v^{-1} S_v C_v\).

**Lemma 3.1** \(T_v = C_v^{-1} S_v C_v\), and \(T_v^n = C_v^{-1} \tilde{T}^n\) for any \(n \in \mathbb{Z}_+\).

**Proof.** Straightforward. Note only that the map \(C_v C_v^{-1}\) needs not to be identical, example:

\[
C_v C_v^{-1}(10_{v-1} 0_1) = (10_v 1).
\]

Observe that the map \(\tilde{T}\) acts on \(X_v\) in exactly the same way as \(T\) acts on the space of binary sequences, namely \(\tilde{T}\) moves each particle by one position forward if there is no particle there or the particle preserves its position otherwise. So the only difference is that now we have \(v\) different types of zeros, instead of the only one type in the case \(v = 1\).
\( \text{Ind}(a) := \begin{cases} -v & \text{if } a = 1 \\ i & \text{if } a = 0 \end{cases} \), 
\( I(A, i) := \max \{ k < i : \sum_{j=k+1}^{i} \text{Ind}(A_j) < 0 \} \),

\( \Omega^n := \{ A \in A^n M : A_n = 1, I(A, n) = 1 \} \),

where \( A_j \) is (as usual) the \( j \)-th element of the word \( A \). Consider a map \( \Gamma \) defined on words of length \( n \in \mathbb{Z}_+ \) as follows: \( (\Gamma A)_i := (\overline{T} A)_{i+1} \) for all \( i = 1, 2, \ldots, n-1 \).

**Lemma 3.2** \( \Gamma : \Omega^n \rightarrow \Omega^{n-2-\xi} \), where \( 0 \leq \xi < n-1 \). The life-time of the cluster of particles in the end of a word \( A \in \Omega^n \) is equal to \( (\rho(A, 1) \cdot |A| - 1) \).

**Proof** follows from the same argument as the one of Lemma 2.4. The only difference is that due to the action of \( \Gamma \) the number of elements in \( \Gamma A \) may become smaller than \(|A| - 2\), since the action of \( C_v C_v^{-1} \) may decrease the number of 0s. On the other hand, during the one iteration of the map \( \Gamma \) only one element 1 disappears from (the right hand side) of \( A \), i.e. \( \rho(A, 1) \cdot |A| = \rho(\Gamma A, 1) \cdot |\Gamma A| + 1 \). Therefore the number of iterations needed for the cluster of particles in the end of the word \( A \) to disappear is equal to the number of ones in the word \( A \) minus one. \( \Box \)

\[
\begin{align*}
A &= \begin{pmatrix} 0_2 & 0_2 & 0_1 & 1 & 0_1 & 1 & 0_1 & 1 \\
\Gamma^1 A &= \begin{pmatrix} 0_2 & 0_2 & 1 & 0_1 & 1 & 1 \\
\Gamma^2 A &= \begin{pmatrix} 0_1 & 0_2 & 1 & 1 \\
\Gamma^3 A &= \begin{pmatrix} 0_2 & 1 \\
\end{pmatrix}
\end{align*}
\]

Example of the action of \( \Gamma^i \) on \( \Omega^3 \) with \( v = 2 \).

**Proof** of Theorems 1.1, 1.2, 1.3 for the case \( v > 1, M = 1 \) follows immediately from Lemmata 3.1, 3.2 and the reduction to the case \( v = 1 \) obtained there. \( \Box \)

Consider now a special case of *superfast* particles corresponding to the choice of maximal velocity \( v = \infty \). Denote

\( X^{(\infty)} := \{ x \in X : \forall n \in \mathbb{Z} \; \exists m, m' > |n| : x_m = 1, x_{-m'} = 0 \} \),

i.e. the set of binary configurations having no infinitely long right ‘tails’ of zeros or left ‘tails’ of ones. Then the maps \( T_{\infty}, T_{\infty}^\omega : X^{(\infty)} \rightarrow X^{(\infty)} \) are well defined. The substitution rule \( 10 \ldots 0 \rightarrow 10 \ldots 1 \forall i \in \mathbb{Z}_+ \) maps \( X^{(\infty)} \rightarrow X^{(\infty)} \). Strictly speaking, the latter has an infinite alphabet, however all arguments applied in the case of finite \( v \) work as well. Moreover here the situation is even simpler, because between each pair of consecutive ones there is only one zero with a certain finite index: \( \ldots 10_i \ldots 10_j \ldots \) Thus the dynamics of \( (T_{\infty}, X_{\infty}) \) is equivalent to the dynamics of free particles, which gives the flux \( \Phi_\pm(x) = 1 - \rho_\pm(x, 1) \).

**4 Dynamics of multi lane flows** \( (T_{v, M}, X_M) \).

**Reduction of** \( T_{1, M} \) **to the direct product of** \( M \) **maps** \( T \)

The model of a muti lane flow of slow particles on a finite lattice has been introduced in [12] and generalized for the case of an infinite lattice \( \mathbb{Z} \) in [3], where statistical properties of regular
initial configurations have been obtained. However the approach used in [3] does not allow to study the dynamics of general initial configurations, which we shall consider in this Section using a completely different method.

Our first aim is to redistribute a configuration \( x \in X_M \) into \( M \) binary configurations \( \{x^{(j)}\} \subseteq X = X_1 \bigoplus \cdots \bigoplus X_M \), such that \( T^{(M+1)} = \sum_j T^{(j)} \) for all \( t \in \mathbb{Z}_+ \cup \{0\} \), where the notation \( x = \sum_j x^{(j)} \) means that \( x_i = \sum_j x^{(j)}_i \) for each \( i \in \mathbb{Z} \). To solve this problem we introduce a sawtooth redirection \( S_l : X_M \rightarrow (X_1)^M \) with \( S_l x = \{x^{(j)}\}_{j=1}^M \) of a configuration \( x \in X_M \) to a collection of binary configurations \( \{x^{(j)}\}_{j=1}^M \) with the starting point at site \( l \in \mathbb{Z}_+ \):

\[
x^{(j)}_i := \begin{cases} 
1 & \text{if } i \geq l \text{ and } j \in (\bigoplus_{k=1}^{i-1} x_k, \bigoplus_{k=i}^{M} x_k) \\
1 & \text{if } i < l \text{ and } j \in (\bigoplus_{k=1}^{i-1} (-x_k), \bigoplus_{k=i+1}^{M} (-x_k)) \\
0 & \text{otherwise,}
\end{cases}
\]

where \( a \oplus b := (a + b - 1) \mod M + 1 \) and \( \bigoplus_{i=1}^{M} x_i := x_n \oplus \cdots \oplus x_m \). In other words, for the configuration \( x \in X_M \) we construct a beinfinite 'staircase' starting from the site \( l \) with the \( i \)-th stair of height \( x_i \) and then redistribute the result modulo \( M \) (preserving the site number) among \( M \) binary configurations \( \{x^{(j)}\}_{j=1}^M \).

With some abuse of notation we shall refer to \( (S_l x)^{(j)} \equiv x^{(j)} \) as the \( j \)-th lane of \( S_l x = \{x^{(j)}\}_{j=1}^M \) and denote the action of the direct product of maps \( T^v \) applied at \( S_l x \) as \( T^v S_l x := \{T^v x^{(j)}\}_{j=1}^M \).

Example for the case \( v = 1 \), \( M = 3 \) and the starting site \( l \) defined by the relation \( x[l-1, l+1] = 211 \):

\[
S_l(\ldots 1121121 \ldots) = \ldots 01010101 \ldots \xrightarrow{T_{1,3}} \ldots 01010101 \ldots = S_{l+1}(\ldots * 112121 * \ldots), \ldots 01010101 \ldots \xrightarrow{T_{1,3}} \ldots 01010101 \ldots
\]

where the unknown positions are marked by *.

Symbolically the sawtooth redirection is shown in Fig. 2(b) by curvilinear lines corresponding to sawtooth rows of ones, open circles mark the intersections of these lines with the 'lanes' \( j, j' \), i.e. the positions where \( x^{(j)} \) or \( x^{(j')} \) are equal to 1 (all other positions on these lanes are occupied by zeros).

**Theorem 4.1** For any \( x \in X_M \) and \( l \in \mathbb{Z}_+ \) and \( S_l(x) \equiv \{x^{(j)}\}_{j=1}^M \) we have

(a) \( x = \sum_j (S_l x)^{(j)} \),

(b) \( |\rho(x^{(j)}[n+1, n+k]1) - \rho(x^{(j')}[n+1, n+k]1)| \leq 1/k \) \( \forall j, j' \in \{1, \ldots, M\}, n \in \mathbb{Z}_+ \) and \( k \in \mathbb{Z}_+ \),

(c) \( S_{l+k} x = \{(S_l x)^{(j+k)}\}_{j=1}^M \) \( \forall k \in \mathbb{Z}_+ \),
depend on \(i\),
\[
(e) \ T_{S_l}x = S_{i+\xi}(T_{1,M}x) \text{ for some } \xi \in \{0, 1\}.
\]

**Proof.** The statement (a) follows immediately from the definition of the sawtooth redirection, because during the redirection each particle preserves its position \(i\).

The property (b) is equivalent to the assumption that

\[
\left| \sum_{i=1}^{k} x_n^{(j)}(i) - \sum_{i=1}^{k} x_n^{(j')}(i) \right| \leq 1,
\]

i.e. that the number of particles in the same segment of different `lanes' \(j, j'\) can differ at most by 1. According to the `sawtooth redirection' for any given finite segment of integers \(n + 1, n + 2, \ldots, n + k\) the number of intersections of the curvilinear lines in Fig. 2(b) with the horizontal line at height \(j\) differs from number of intersections with the horizontal line at height \(j'\) at most by one. This immediately yields the property (b).

The collection of binary configurations \(S_l(x)\) has a row of ones at site \(i\) of height \(k\) if and only if \(x = k\), and the change of the starting point \(l\) of the redirection only changes cyclically the starting point 1 of the enumeration of lanes \(x^{(1)}\). This proves the property (c).

Observe now that the definition of \(S_l(x)\) is equivalent to the existence of a partition of \(\mathbb{Z}\) into segments \([i_-, i_+]\) such that \(x^{(1)}(i_-) = 1, x^{(M)}(i_+) = 1\) (except for the most left segment where \(i_- = -\infty\) and the most right one where \(i_+ = \infty\)) and for any \(1 < j < M\) there exists the only one \(i \in [i_-, i_+]\) such that \(x^{(j)}(i) = 1\). Indeed, according to the `sawtooth redirection' the curvilinear lines in Fig. 2(b) have the property that the intersection with the horizontal line at height \(j\) occurs not earlier than with the horizontal line at height \(j' > j\) (the curvilinear lines may have vertical segments). To simplify the notation we shall say that \(S_l(x)\) is monotonous on \([i_-, i_+]\).

Consider the interval of monotonicity \([i_-, i_+]\) which starts from \(i\), i.e. \(i_- = i\). We set \(\xi\) to be equal to the minimum of the number of not occupied positions in \(x^{(1)}\) ahead of the site \(i_-\) (which is occupied by 1). Then under the action of \(T_0\), the particle at the site \(i_-\) of the 1-st lane moves \(\xi\) positions to the right. Observe that all particles on the other lanes in the segment \([i_-, i_+]\) have at least \(\xi\) not occupied positions ahead of them, and therefore all these particles will move at least \(\xi\) positions to the right. Thus to prove that the monotonicity is preserved it is enough to note that the particle on the lane \(M\) cannot move further to the right than the first particle on the first lane of the next interval of monotonicity. Indeed, the latter is a trivial consequence of the definition of intervals of monotonicity. This finishes the proof of the statement (d) except the last part, which follows from the statement (c).

To prove the statement (e), observe that by the definition of the map \(T_{1,M}\) (see Section 1) a particle at the site \(i\) of the lane \(j\) can switch to the lane \(j'\) if and only if \(x^{(1)}(i, i + 1) = 11\) and \(x^{(1)}[i, i + 1] = 00\), which contradicts to the definition of the intervals of monotonicity. Therefore under the sawtooth redirection no particle in \(S_l(x)\) will change its lane. \(\square\)

**Corollary 4.1** The sawtooth redirection gives a simple constructive way to rearrange vehicles in a multi lane traffic flow between lanes (preserving their positions in the flow) to achieve the maximal available flux.

According to Theorem 4.1, (d) the map \(x \rightarrow \sum_j T_v(S_l x)^{(j)}\) is well defined as a map from \(X_M\) into itself and does not depend on the choice of the starting site \(l \in \mathbb{Z}\). Moreover, it can be shown that this formula coincides with (1.1) in the case \(v = 1\), and it clearly coincides with \(T_v\) in the case \(M = 1\). Therefore we use this relation as a definition of the dynamics of a general multi lane flow in the case \(v, M > 1\), namely we set \(T_{v,M}x := \sum_j T_v(S_0 x)^{(j)}\).
redirection, which gives the reduction to the one-lane case. It remains to show that the statistics
of more general words \( A \subset X_M \) with \( |A| = 1 \) might be preserved under dynamics. The reason
of this is that if \( M > 1 \) the multiplicities might not be preserved. Indeed, let \( a \in A_M \setminus \{0, 1\} \).
Then \( \rho(\langle a(M-a+1)0 \rangle, a) = \frac{1}{3}(1 + \lfloor (M - a + 1)/a \rfloor + 0) \), while
\[
\rho(T_{1,M}(\langle a(M-a+1)0 \rangle, a) = \rho(\langle (a-1)(M-a+1) \rangle, a)
\]
\[
= \frac{1}{3}(0 + 0 + [ (M - a + 1)/a ] + 0) < \rho(\langle a(M-a+1)0 \rangle, a).
\]
\[
\square
\]
\textbf{Proof} of Theorems 1.2,1.3 for the case \( v, M > 1 \). Consider a configuration \( x \in X_M \). According
to Theorem 4.1,(b) for \( S_0x = \{x^{(j)}\}_{j=1}^M \) we have \( \forall n, m \in \mathbb{Z}_+ \) that
\[
|\rho(x^{(j)}[-n, m], 1) - \rho(x^{(j')}[-n, m], 1)| \leq \frac{1}{m+n+1}.
\]
Thus going to the limit as \( n, m \to \infty \) and using Theorem 4.1,(a) we get \( \rho_\pm(x^{(j)}, 1) = \frac{1}{M} \rho_\pm(x, 1) \)
for each \( j \in \{1, \ldots, M\} \). Therefore the application of the results obtained in Sections 2,3 in the
case of one-lane flows (i.e. in the case of the map \( T_v \)) proves the statements under question. \( \square \)

\section{5 Rate of convergence: (space) periodic, regular, and typical
initial configurations}

In this section we study the rate of convergence of various statistics to the corresponding limit
values whose existence have been established in Theorems 1.3,1.2. Since we have shown that
the analysis of \( T_{v,M} \) in all cases can be reduced to the case of \( v = M = 1 \), we consider in this
section only the dynamics of slow particles and shall consider the proof of Theorem 1.4 only for
this case.

We start with periodic in space configurations. Clearly each \( n \)-periodic in space configuration
\( x \in X \) can be represented in the form \( x := \langle A \rangle \) with a binary word \( A \) of length \( |A| = n \).

\textbf{Lemma 5.1} Let \( x := \langle A \rangle \) with \( |A| = n \), then \( \rho_\pm(x, a) = \rho(A, a) \) for \( a \in \{0, 1\} \). The space of
\( n \)-periodic in space configurations is invariant under the action of the map \( T \) and after at most
\( \lfloor n/2 \rfloor + 1 \) iterations any configuration from this space belongs to \( \text{Free} \cup \text{Free}^* \).

\textbf{Proof.} Straightforward. \( \square \)

The only nontrivial question related to this space is the length of the transient period for a
given configuration \( x \in X \).

\textbf{Lemma 5.2} Let \( x := \langle A \rangle \) with \( |A| = n \) and \( \rho(A, 1) \leq 1/2 \) and let \( B \) be the longest minimal
word in \( A \). Then the length of the transient period is equal to \( |B|/2 - 1 \).

\textbf{Proof.} This is an immediate consequence of Lemma 2.4. \( \square \)

Consider now a generalization of the space of periodic in space configurations – the space of
regular configurations, proposed in [2, 3]. This space is defined as follows:

\[ \text{Reg}(r, \psi) := \{ x \in X : |\rho(x[-n, m], 1) - r| \leq \psi(n + m) \ \forall n, m \in \mathbb{Z}_+ \}, \]
strictly decreasing.

**Lemma 5.3** Let \( x \in \text{Reg}(r, \psi) \), then the density \( \rho(x, 1) := r \) is well defined, and if \( \neq 1/2 \) then there is a constant \( \tau \) such that the life-time of any cluster of particles in \( x \) does not exceed \( \tau \).

**Proof.** First, observe that if \( x \in \text{Reg}(r, \psi) \) then we have

\[
\rho_\pm(x, 1) = \lim_{n,m \to \infty} \left( \sup \inf \rho(x[-n, m], 1) = r, \right.
\]

and thus \( \rho(x, 1) = r \) is well defined. Assume now that \( x \in \text{Reg}(r, \psi) \) with \( r < 1/2 \), then, since \( \psi(n) \to 0 \) as \( n \to \infty \), we deduce that there is a positive integer \( \tau \) such that \( \phi(\tau) < 1/2 - r \). Then we have \( \rho(x[n, n + \tau], 1) < 1/2 \) for any \( n \in \mathbb{Z} \), which yields the claim of the lemma due to Lemma 2.8. The case \( r > 1/2 \) follows from the same argument but applying Lemma 2.9 instead. \( \square \)

Now we proceed to study more general initial configurations.

**Lemma 5.4** Let \( x \in X \) satisfies the assumption that there exists a number \( \gamma \in (0, 1) \) such that \( \forall n \in \mathbb{Z}_+ \) and any word \( A \subseteq x[-n, n] \) with \( |A| > 2\gamma n \) we have \( \rho(A, 1) \leq 1/2 \). Then \( \text{dist}(T^t x, \text{Free}) \leq 2^{-t/\gamma + 1} \) for any \( t \in \mathbb{Z}_+ \). If \( x^* \) satisfies the same assumption, then we have \( \text{dist}(T^t x, \text{Free}^*) \leq 2^{-t/\gamma + 1} \).

**Proof.** Consider only those \( n \in \mathbb{Z}_+ \) for which the largest minimal words containing a cluster of particles in \( x[-n, n] \) also belong to \( x[-n, n] \). By the assumption of Lemma the length of the largest minimal interval containing in the segment \( x[-n, n] \) does not exceed \( 2\gamma n \). Therefore the corresponding clusters of particles with disappear after at most \( \gamma n \) iterations, and thus for all sufficiently large \( t \in \mathbb{Z}_+ \) all particles in the segment \( T^t x[-t/\gamma, t/\gamma] \) will become free. Thus the closest to the origin nonfree particle can appear not earlier as at site \( t/\gamma \), which gives the desired estimate of the rate of convergence. The second statement follows from the same argument applied to the dual map. \( \square \)

**Lemma 5.5** Let \( x \in X \) satisfies the same assumption as in Lemma 5.4, then

\[
\limsup_{n \to \infty} \frac{1}{2n} \sum_{i=-n}^{n} V(T^n x, 1) = F_{1,1}(\rho(x, 1)),
\]

**Proof.** Observe that \( \frac{1}{2n} \sum_{i=-n}^{n} V(x, 1) = \rho(x[-n, n], 10) \). Applying the same argument as in the proof of Lemma 5.4 we see that after \( n \) iterations the segment \( T^n x[-n/\gamma, n/\gamma] \) contains only free particles. Therefore \( \rho(x[-n, n], 10) = \rho(x[-n, n], 1) \), which yields the desired equality. \( \square \)

**Corollary 5.6** The statements of Lemmata 5.4,5.5 remain valid if instead of \( \forall n \in \mathbb{Z}_+ \) we assume that \( n \) belongs to the subset of \( \mathbb{Z}_+ \) of density 1.

**Lemma 5.7** \( \forall \gamma \in (0, 1) \) for \( \mu_\rho \)-a.a. configurations \( x \in X \) the set of \( n \in \mathbb{Z}_+ \), for which any word \( A \subseteq x[-n, n] \) with \( |A| > 2\gamma n \) satisfies the inequality \( \rho(A, 1) \leq 1/2 \), has the density 1.
all $i \in \mathbb{Z}$. Introduce a sequence of functions $y_n(\tau) := \frac{1}{2n+1} \sum_{i=-n}^{n} [2n \tau] x_i$ depending on a real variable $\tau \in [\gamma, 1]$, and consider a functional
\[
\phi(y(\tau)) := \sup_{\tau \in [0,1]} \sup_{\gamma \leq s \leq 1-\tau} \frac{1}{s} (y(\tau+s) - y(\tau))
\]
defined in Skorohod space of functions $y(\tau)$. Then the quantity under question is the probability $\mathcal{P}(\phi(y_n(\tau))) \leq 1/2$ $\forall \tau \in [\gamma, 1]$. Since $y_n(\tau)$ converges in probability for a given $\tau$ to $\tilde{y}(\tau) := n \tau$ and the functional $\phi$ is continuous, $\phi(y_n(\tau))$ converges to $\phi(\tilde{y}(\tau))$ (functional law of large numbers). Thus we have

\[
\mathcal{P}(\phi(y_n(\tau))) \leq 1/2 \quad \forall \tau \in [\gamma, 1] \rightarrow \mathcal{P}(\phi(\tilde{y}(1))) \leq 1/2 = 1,
\]
where the rate of convergence $(\mathcal{P}(\phi(y_n(1))) > 1/2) \overset{\text{as} \ n \to \infty}{\longrightarrow} \sqrt{2p(1-p)}$ follows by the combination of the large deviation principle for the functions $y_n(\tau)$ and the contraction principle (see, e.g., [5]).

\[\square\]

**Corollary 5.8** Results of Lemmata 5.4, 5.5, 5.7 prove Theorem 1.4 in the case $v = M = 1$.

### 6 Dynamics of measures and chaoticity

In this section we shall study the action of the map $T_{v,M}$ in the space $\mathcal{M}(X_M)$ of probabilistic measures on $X_M$. This action is defined as follows: $T_{v,M} \mu(Y) := \mu(T_{v,M}^{-1} Y)$ for a measure $\mu \in \mathcal{M}(X_M)$ and a measurable subset $Y \subseteq X_M$. A measure $\mu \in \mathcal{M}(X_M)$ is called translation invariant if it is invariant with respect to the action of the shift map $\sigma : X_M \rightarrow X_M$.

**Lemma 6.1** If $\mu \in \mathcal{M}(X_M)$ is translation invariant then this property holds for $T_{v,M}^{i} \mu \forall i \in \mathbb{Z}_+$. 

**Proof.** We have $T_{v,M}^{i} \mu(Y) = \mu(T_{v,M}^{-i} Y) = \mu(T_{v,M}^{-i} \sigma Y) = T_{v,M}^{i} \mu(\sigma Y)$. \[\square\]

One might expect that under the action of the map $T_{v,M}$ any translation invariant measure should converge to a Bernoulli one. Indeed,

\[
T \mu_p \left( x \in X : x_0 = 1 \right) = \mu_p \left( x \in X : [0,1] = 11 \right) + \mu_p \left( x \in X : (-1,0] = 10 \right)
\]

\[
= \mu_p \left( x \in X : [0,1] = 11 \right) + \mu_p \left( x \in X : [0,1] = 10 \right) = \mu_p ( x \in X : x_0 = 1 ).
\]

On the other hand, the product structure is not preserved even in the case of the model of slow particles.

**Lemma 6.2** The measure $T \mu_p$ is not a product one for any $0 < p < 1$.

**Proof.** We have

\[
T \mu_p \left( x \in X : [0,1] = 11 \right) = \mu_p \left( x \in X : [0,2] = 111 \right) + \mu_p \left( x \in X : [-1,2] = 1011 \right)
\]

\[
= p^3 + p^3(1-p) = p^3(2-p) \neq p^2 = \mu_p \left( x \in X : [0,1] = 11 \right).
\]

Thus the measure $T \mu_p$ does not have the product structure. \[\square\]

\[\text{The idea of this construction, based on the large deviation principle, was proposed by A. Puhalskii.}\]
preserved under dynamics. Indeed,

\[ T_\nu \mu_p (x \in X : x_0 = 1) = \mu_p (x \in X : x[0, 1] = 11) + \sum_{i=1}^{\nu} \mu_p (x \in X : x[-1, 0] = 10_i) \]

\[ = p^n + p(1-p) + \ldots + p(1-p)^v = p + \sum_{i=2}^{\nu} \left( 1 - p \right)^i \]

\[ > p = \mu_p (x \in X : x_0 = 1). \]

Note that in the case of the slow particles model \((T_1, X)\) some results about the set of \(T_{1,1}\)-invariant measures and mathematical expectations of the limit flux with respect to them were studied in [1].

In [2] it has been proven that the dynamical system \((T_{1,M}, X_M)\) is chaotic in the sense that its topological entropy is positive. Moreover, this paper gives an asymptotically exact \((as M \to \infty)\) representation for the entropy. The extension of this result to the case \((T_{1,M}, X_M)\) with \(v > 1\) is straightforward.

7 Passive tracer in the 1-lane flow of fast particles

Let \(T_v^t, v \geq 1\) describes the 1-lane flow of particles and let at time \(t\) the passive tracer occupies the position \(i\). Then before the next time step of the model of the flow the tracer moves in its chosen direction to the closest (in this direction) position of a particle of the configuration \(T_v^t x\). For example, if the going forward tracer occupies the position 2 and the closest particle in this direction occupies the position 5, then the tracer moves to the position 5. Then the next iteration of the flow occurs, the tracer moves to its new position, etc.

To be precise let us fixed a configuration \(x \in X\) with \(\rho_-(x, 1) > 0\) and introduce the maps \(\tau^\pm_x : \mathbb{Z} \to \mathbb{Z}\) defined as follows:

\[ \tau^+_x i := \min \{ j : i < j, x_j = 1 \}, \quad \tau^-_x i := \max \{ j : i > j, x_j = 1 \}. \]

Then the simultaneous dynamics of the configuration of particles (describing the flow) and the tracer is defined by the skew product of two maps – the map \(T_v\) and one of the maps \(\tau^\pm\), i.e.

\[ (x, i) \to T_v T_v(x, i) := (T_v x, \tau_x^\pm i), \]

acting on the extended phase space \(X \times \mathbb{Z}\). The sign ‘+’ or ‘−’ here corresponds to the motion along or against the flow. We define the average (in time) velocity of the tracer \(V(t, x)\) as \(S(t) / t\), where \(S(t)\) denotes the total distance covered by the tracer (which starts at the site 0) up to the moment \(t\) with the positive sign if the tracer moves forward, and the negative sign otherwise.

**Theorem 7.1** Let \(x \in \{ x \in X : \text{dist}(T_v^t x, \text{Free} \cup \text{Free}^*) \leq 2^{-t/\gamma + 1} \} \) for all \(t \in \mathbb{Z}_+\) and some \(0 < \gamma < 1\). If \(0 < \rho_+(x, 1) \leq \gamma \frac{1}{v+1}\), then \(V(t, x) \underset{t \to \infty}{\to} v\) if the tracer moves along the flow (i.e. in the case \(T_1\)), and \(\lim_{t \to \infty} \left( \sup \limits_{t \in \mathbb{Z}_+} V(t, x) \right) = \frac{-1}{\rho_\pm (x, 1)} + 1\) in the opposite case. If \(\rho_-(x, 1) > 1 - \frac{1}{v+1}\) and the tracer moves against the flow then \(V(t, x) \underset{t \to \infty}{\to} -1\).

**Remark.** The assumption about the initial configurations is satisfied for \(\mu_p\)-a.a. \(x \in X_M\) (see Theorem 1.4).

**Proof.** Since we assume that \(T_v^t x\) converges to the attractor \(\text{Free} \cup \text{Free}^*\) with the exponentially fast rate, then at the moment \(t \in \mathbb{Z}_+\) we have an exponentially long (in \(t\)) interval of the
we shall show that $V(t, x)$ converges to a constant, then to study its value we can restrict the analysis to the case $x \in \text{Free} \cup \text{Free}^\circ$.

Under the assumption $0 < \rho_+(x, 1) \leq \frac{1}{v+1}$ we have $T_v^t x \overset{t \to \infty}{\to} \text{Free}_n$. In the case of $T_v^t$ the tracer will run down one of the particles and will follow it, but cannot outrun. Indeed after each iteration of the flow this free particle occurs exactly $v$ positions ahead of the tracer. Thus $V(t, x) \overset{t \to \infty}{\to} v$.

Consider now the case when the tracer moves backward with respect to the flow. Then each time when the tracer encounters a particle, on the next time step this particle moves in the opposite direction and does not interfere with the movement of the tracer. We assume again that $x \in \text{Free}_n$ and consider the case $0 < \rho_-(x, 1) \leq \frac{1}{v+1}$. If on the spread of length $n$ there are $m$ particles, i.e. $m$ obstacles for the tracer then the average velocity on this segment is equal to $\frac{n-m}{m}$. Going to the limit as $n \to \infty$ we obtain the desired estimate.

It remains to consider the case $\rho_-(x, 1) > 1 - \frac{1}{v+1}$ and thus $T_v^t x \overset{t \to \infty}{\to} \text{Free}_n^\circ$, i.e. to the flow where all holes move at maximal velocity $-v$. Thus after each iteration the tracer moves exactly by one position to the left (since it never can encounter a hole), which gives the limit velocity $-1$. \hfill \Box

Observe that the motion against the flow is efficient only in the case of low density of particles when $\rho_-(x, 1) \leq \frac{1}{v+1}$. On the other hand, in the high density region in the case of the motion along the flow and in the region $\frac{1}{v-1} < \rho_-(x, 1) < 1 - \frac{1}{v-1}$ in the case of the motion against the flow the limit velocity of the tracer depends not only on the densities, but also on the fine structure of the configuration $x$. Moreover, this concerns also the case of ‘untypical’ initial configurations with $0 < \rho_-(x, 1) < 1/2 < \rho_+(x, 1)$, when there might be arbitrary long (even infinite) minimal words for both particles and holes.

References


