London

## Coherence and Regularity of Modelled Distributions

Higher structures emerging from renormalisation ESI

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joint work with
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Motivation: Want a systematic understanding of how to glue together deterministic ODE/PDE arguments at larger time (and space) scales with local solution theory from Gubinelli's Branched Rough Paths/Hairer's Theory of Regularity Structures to get a priori bounds on solutions with the aim of getting global in time (and space) well-posedness.

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Recent work: Studying equations with strong damping terms and proving strong "coming down from infinity" type bounds:

The $\Phi^{4}$ equation:

$$
\left(\partial_{t}-\Delta\right) \varphi=-\varphi^{3}+\xi
$$

where formally $\varphi: \mathbb{R}_{+} \times \mathbb{R}^{d} \rightarrow \mathbb{R}$ and $\xi$ is a rough random space-time process (like space-time white noise).

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Previous work on a priori bounds/global well-posedness:
For for $\Phi_{3}^{4}$ : [Mourrat, Weber], [Gubinelli, Hofmanová], [Albeverio, Kusuoka], [Moinat, Weber]
[C., Moinat, Weber] extends analysis to the entire subcritical/super-renormalizable regime.

Rough Differential Equations with strong damping:

$$
\partial_{t} Y(t)=-|Y(t)|^{m-1} Y(t) d t+\sum_{\mu=1}^{d} \sigma_{\mu}(Y(t)) d X^{\mu}(t)
$$

where $m>1, Y: \mathbb{R}_{+} \rightarrow \mathbb{R}^{k}$ and $X=\left(X^{\mu}\right)_{\mu=1}^{d}: \mathbb{R}_{+} \rightarrow \mathbb{R}^{d}$ is a rough ( $\alpha$-Hölder, for $\alpha>0$ but arbitrarily small) driving noise, and $\sigma_{\mu}: \mathbb{R}^{k} \rightarrow \mathbb{R}^{k}$ are relatively nice vector fields.
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Previous work on this class of equations by [Riedel, Scheutzow]. Joint work in progress using approach from SPDE with Bonnefoi, Moinat, and Weber. Example of coming down from infinite bound: if $\sigma_{\mu}$ has a certain class of derivatives bounded and if $Y$ solves the above equation on $[0,1]$ then

$$
\begin{gathered}
\sup _{t \in(0,1]}|Y(t)| \lesssim \max \left\{t^{-\frac{1}{m-1}}, \max _{h \in \mathcal{T}}[\mathbf{X}: h]^{\frac{1}{m \alpha|h|}}\right\} \\
\text { uniformly over the initial data } Y(0)
\end{gathered}
$$

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- Solution: Can construct new spaces of function/distributions that admit good local approximations (non-classical Taylor Expansions) in terms of these iterated integrals - and the equation can be reformulated on this space in a way that makes it locally well-posed there.

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- Solution - Algebra/Combinatorics: Can show that a solution to a Rough Differential Equation has additional relations between these generalised derivatives (coherence - [Bruned, Chevyrev, Preiß, Friz], [Bruned, Chevyrev, C., Hairer] )

Quick overview of branched Rough Paths

- Let $N=\left\lfloor\frac{1}{\alpha}\right\rfloor$, we define $\stackrel{\circ}{\mathcal{T}}$ to consist of all rooted trees with no more than $N$ nodes, each of which is decorated by the set
$\{1, \ldots, d\}$.


- Driving noise along with Iterated integrals encoded by map $\mathbf{X}_{s, t}: \mathcal{T} \rightarrow \mathbb{R}, \mathcal{T} \ni h \mapsto\left\langle\mathbf{X}_{s, t}, h\right\rangle$.

$$
\begin{aligned}
\left\langle\mathbf{X}_{s, t}, e_{i}\right\rangle & =\int_{s}^{t} d X^{i}(r)=X^{i}(t)-X^{i}(s) \\
\left\langle\mathbf{X}_{s, t}, \dot{b}_{j}^{i}\right\rangle & =\int_{s}^{t} \int_{s}^{r_{1}} d X^{i}\left(r_{2}\right) d X^{j}\left(r_{1}\right) \\
\left\langle\mathbf{X}_{s, t}, \dot{j}_{k}^{i}\right\rangle & =\int_{s}^{t} \int_{s}^{r_{1}} \int_{s}^{r_{2}} d X^{i}\left(r_{3}\right) d X^{j}\left(r_{2}\right) d X^{k}\left(r_{1}\right) \\
\left\langle\mathbf{X}_{s, t},{ }_{j}^{i}\right\rangle & =\int_{s}^{t}\left(\int_{s}^{r_{1}} d X^{i}\left(r_{2}\right)\right)^{2} d X^{j}\left(r_{1}\right)
\end{aligned}
$$

- We define $\mathcal{F}$ to be the set of forests of trees in $\mathfrak{T}$. We also set $\mathcal{T}=\{\mathbb{1}\} \sqcup \mathcal{T}$.
forest $f$


Empty forest $\mathbb{1}$
Commutative
product of trees

$$
f=h_{1} h_{2} h_{3}
$$

$$
f \longmapsto[f]_{\mu}=
$$



Can turn forest into a new tree

- We define $\mathcal{F}$ to be the set of forests of trees in $\mathcal{T}$. We also set $\mathcal{T}=\{\mathbb{1}\} \sqcup \mathcal{T}$.


$$
\Delta\left(h_{1} h_{2} \cdots h_{n}\right)=\left(\Delta h_{1}\right)\left(\Delta h_{2}\right) \cdots\left(\Delta h_{n}\right)
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- $\Delta: \operatorname{Span}(\mathcal{F}) \rightarrow \operatorname{Span}(\mathcal{F}) \otimes \operatorname{Span}(\mathcal{F})$ is the Grassman-Larson co-product
- We call $\mathbf{X}$ a branched rough path if for all $h \in \mathcal{T}$,

$$
\begin{aligned}
& {[\mathbf{X}, h] \stackrel{\text { def }}{=} \sup _{0<|s-t|<1}\left|\frac{\left\langle\mathbf{X}_{s, t}, h\right\rangle}{|s-t|^{\alpha|h|}}\right|<\infty} \\
& \text { and }\left\langle\mathbf{X}_{s, u} \otimes \mathbf{X}_{u, t}, \Delta h\right\rangle=\left\langle\mathbf{X}_{s, t}, h\right\rangle
\end{aligned}
$$

Our solution is a Controlled Rough Path: $\mathbf{Y}:[0,1] \rightarrow \operatorname{Span}(\mathcal{T})$, that is a family of local expansions

$$
\mathbf{Y}_{s}=\sum_{h \in \mathcal{T}}\left\langle h, \mathbf{Y}_{s}\right\rangle h=\underbrace{Y_{s} \mathbb{1}+\sum_{h \in \mathcal{T}}\left\langle h, \mathbf{Y}_{s}\right\rangle h . \begin{array}{c}
\text { "generalised } \\
h \text {-derivative } \\
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with the following regularity property, Taylor expansion of

$$
R_{s, t}^{h}=\left\langle h, \mathbf{Y}_{t}\right\rangle-\left\langle\mathbf{X}_{s, t} \otimes h, \Delta \mathbf{Y}_{s}\right\rangle, \text { want }\left|R_{s, t}^{h}\right| \lesssim|s-t|^{(N-|h|) \alpha}
$$

$R_{s, t}^{h}$ should be thought of as Taylor remainder for $h$-derivative of $Y$ with basepoint $s$ and evaluated at $t$.

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Space of controlled rough paths is a vector space where we can solve the equation as a fixed point problem, but in this space there are no clear relations between $R_{s, t}^{h}$ for different $h$.

Can show that solutions to equation solve the non-linear coherence constraint $\left\langle h, \mathbf{Y}_{t}\right\rangle=\Upsilon[h]\left(Y_{s}\right)$ for some functions $\Upsilon[h](\cdot)$ built inductively in $h$ - if $h=\left[h_{1} \cdots h_{n}\right]_{\mu}$ then

$$
\Upsilon[h] \approx\left(D^{n} \sigma_{\mu}\right) \prod_{j=1}^{n} \Upsilon[h] \text { with base cases } \Upsilon[\quad]=\sigma_{\mu}
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Combining this with the adjoint relation $\langle\tilde{f} \otimes h, \Delta \bar{h}\rangle \approx\langle\tilde{f} \curvearrowright h, \bar{h}\rangle$ allows us to show that

$$
\left|R_{s, t}^{h}\right| \lesssim\left|\nabla \Upsilon[h]\left(Y_{s}\right)\right| \cdot\left|R_{s, t}^{\mathbb{1}}\right|+\text { higher order terms }
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which allows us to close our ODE argument!

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## Thanks for listening!

